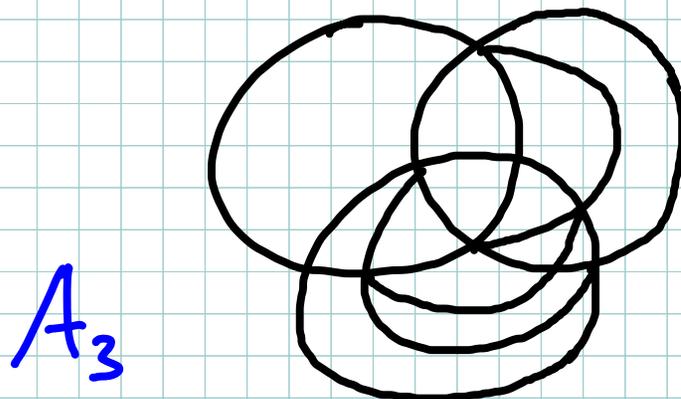
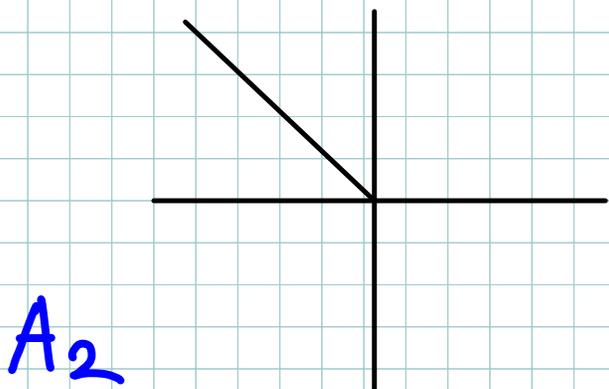


On maximal green sequences



Thomas Brüstle, Herstmonceux 2016
(joint with S.Hermes, K.Igusa, G.Todorov)

1) Setup: Stability Conditions



A. King: Q quiver, n vertices

$\theta: \mathbb{Z}^n \rightarrow \mathbb{R}$ additive

$$\mathbb{Z}^n \cong K_0(\text{rep } Q)$$

$\underbrace{\quad}_v$
 $\{\text{positive roots}\}$

Q quiver, n vertices

$$q: \mathbb{Z}^n \rightarrow \mathbb{Z}, x \mapsto \sum_{i=1}^n x_i^2 - \sum_{i \rightarrow j} x_i x_j$$

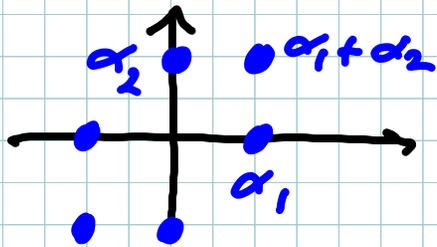
quadratic form

q positive definite $\Leftrightarrow Q$ Dynkin

$M \in \mathbb{Z}^n$ real root $\Leftrightarrow q(M) = 1$

$Q = \overset{1}{\circ} \longrightarrow \overset{2}{\circ}$ type A_2 , $q(x) = x_1^2 + x_2^2 - x_1 x_2$

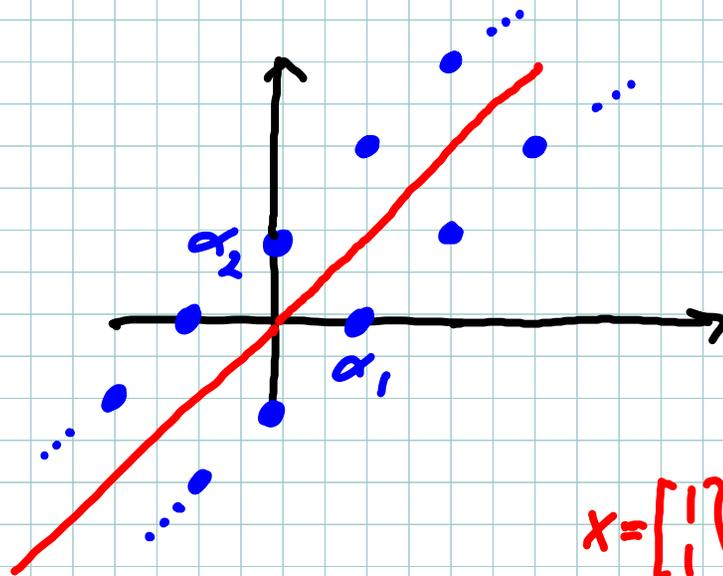
positive real roots are $\alpha_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$, $\alpha_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$, $\alpha_1 + \alpha_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$



$M \in \mathbb{Z}^n$ real root $\Leftrightarrow \varphi(M) = 1$

$Q = \begin{smallmatrix} 1 \\ 0 \end{smallmatrix} \Rightarrow \begin{smallmatrix} 2 \\ 0 \end{smallmatrix}$ affine type A, $\varphi(x) = x_1^2 + x_2^2 - 2x_1x_2$

real roots are $\left\{ \begin{bmatrix} u \\ u+1 \end{bmatrix}, \begin{bmatrix} u+1 \\ u \end{bmatrix} : u \in \mathbb{Z} \right\}$



$x = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \Rightarrow \varphi(x) = 0$

"imaginary root"

A. King: Q quiver, n vertices

$\theta: \mathbb{Z}^n \rightarrow \mathbb{R}$ additive

$M \in \mathbb{Z}^n$ positive root

M θ -semi-stable if $\theta(M) = 0$ and $\theta(N) \geq 0$

for all N positive root, subrepresentation of M

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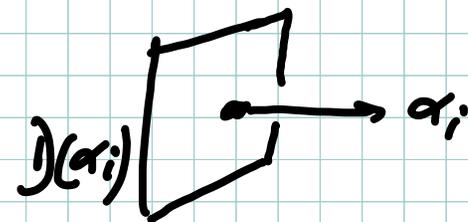
$$\mathbb{R}^n \cong \{ \theta_y \mid y \in \mathbb{R}^n \} \quad \theta_y : \mathbb{R}^n \rightarrow \mathbb{R}, x \mapsto (x, y)$$

space of stability functions

For M pos. real root, $\mathcal{D}(M) = \{ \theta_y : M \text{ is } \theta_y\text{-semi-stable} \}$

$M = \alpha_i$ simple root: $\nexists N \subset M$

$M = \alpha_i$ θ_y -stable $\Leftrightarrow (y, \alpha_i) = 0$



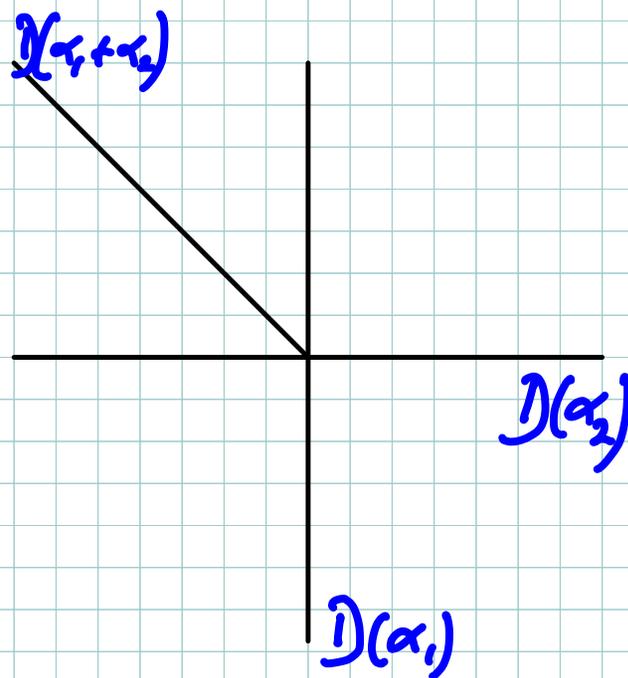
example: $Q = \begin{matrix} 1 & & 2 \\ \circ & \longrightarrow & \circ \end{matrix} A_2$

$M = \alpha_1 + \alpha_2$ pos. real root : $M = \begin{matrix} \alpha_1 & \alpha_1 \text{ quotient} \\ \downarrow & \\ \alpha_2 & \alpha_2 \text{ submodule} \end{matrix}$

$$(\gamma, M) = 0 \Leftrightarrow \gamma_1 + \gamma_2 = 0$$

$$D(M) = \{ \theta_\gamma : \gamma_1 + \gamma_2 = 0, \gamma_2 \geq 0 \}$$

Space of stability functions:



Chambers = components of

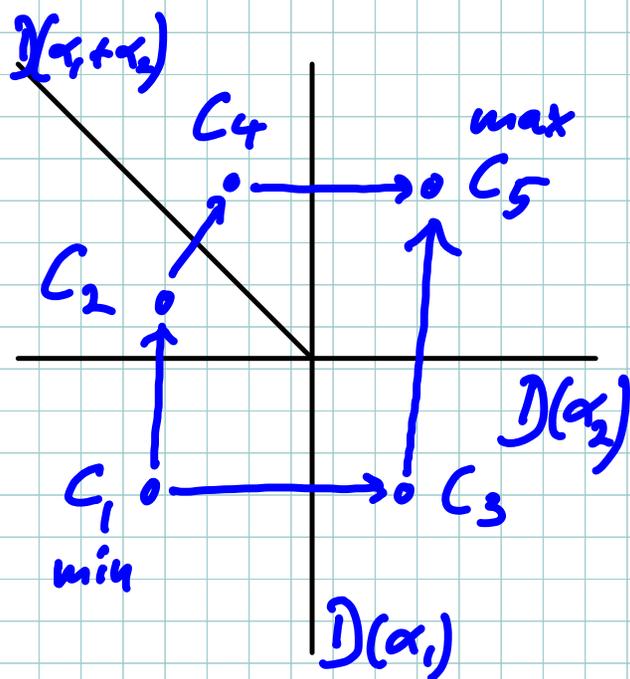
$$\mathbb{R}^n \setminus \bigcup_{M \text{ pos. real root}} D(M)$$

example: $Q = \overset{1}{\circ} \rightarrow \overset{2}{\circ} \quad A_2$

Space of stability functions:

$$C_{\min} = \{y \in \mathbb{R}^n : (y, \alpha_i) < 0 \quad \forall i=1, \dots, n\}$$

$$C_{\max} = \{y \in \mathbb{R}^n : (y, \alpha_i) > 0 \quad \forall i=1, \dots, n\}$$



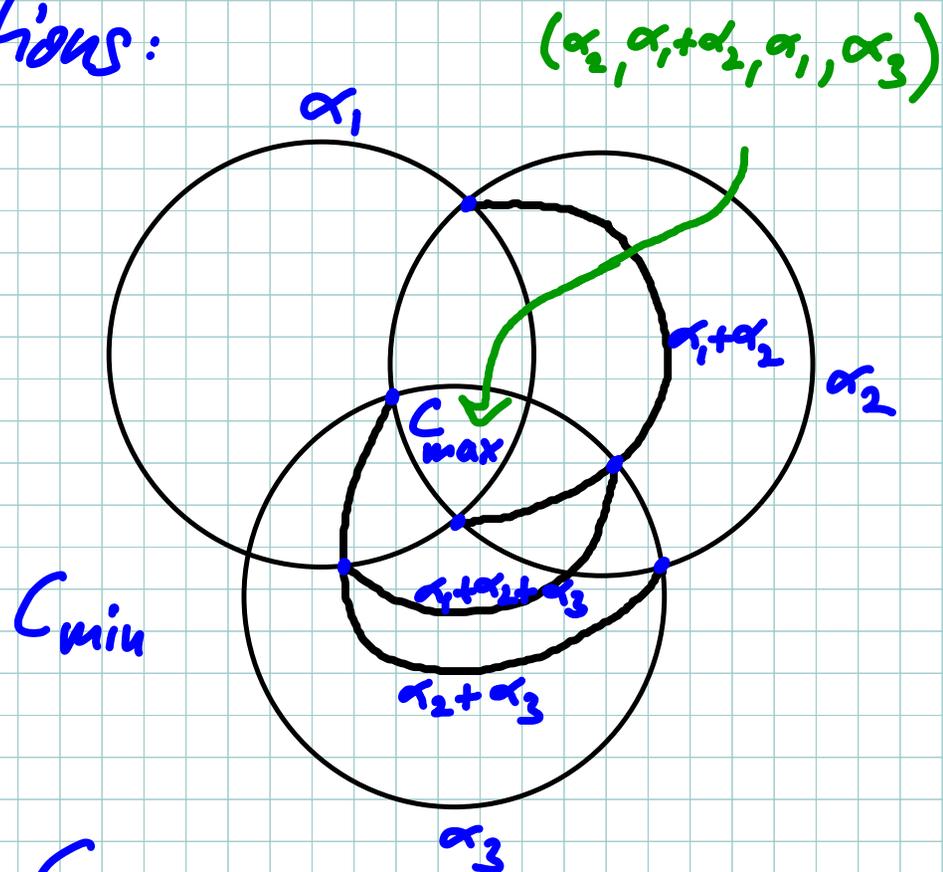
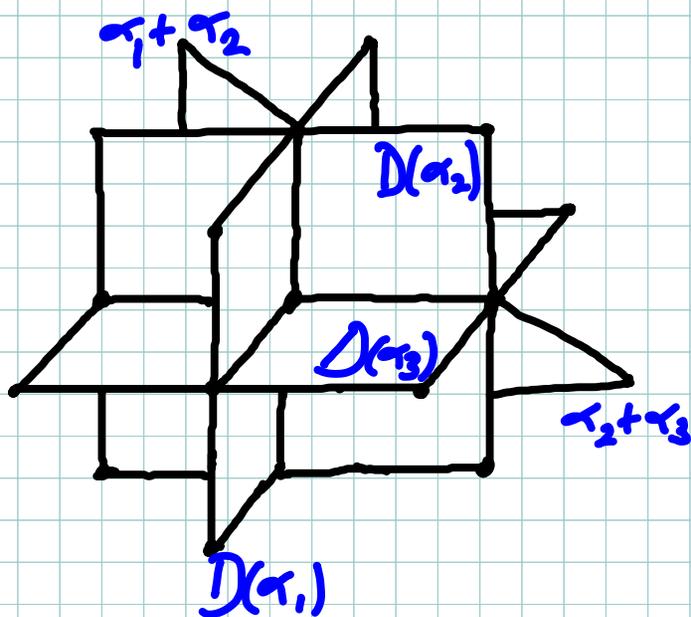
MGS = maximal green sequence

= path from C_{\min} to C_{\max} passing through walls $D(\alpha_i)$ separately and in positive direction: $(y, \alpha_i) < 0 \rightsquigarrow (y, \alpha_i) > 0$

A_2 has 2 MGS: $(\alpha_2, \alpha_1 + \alpha_2, \alpha_1)$ and (α_1, α_2)

example: $Q = \overset{1}{\circ} \rightarrow \overset{2}{\circ} \rightarrow \overset{3}{\circ} \quad A_3$

Space of stability functions:



$14 = \text{Cat}(4)$ chambers C_i

9 MGS

lengths $3 \leq l \leq 6$

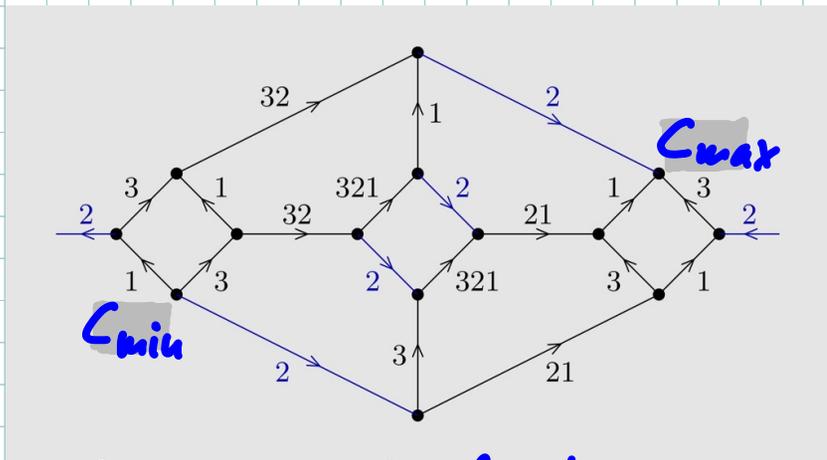
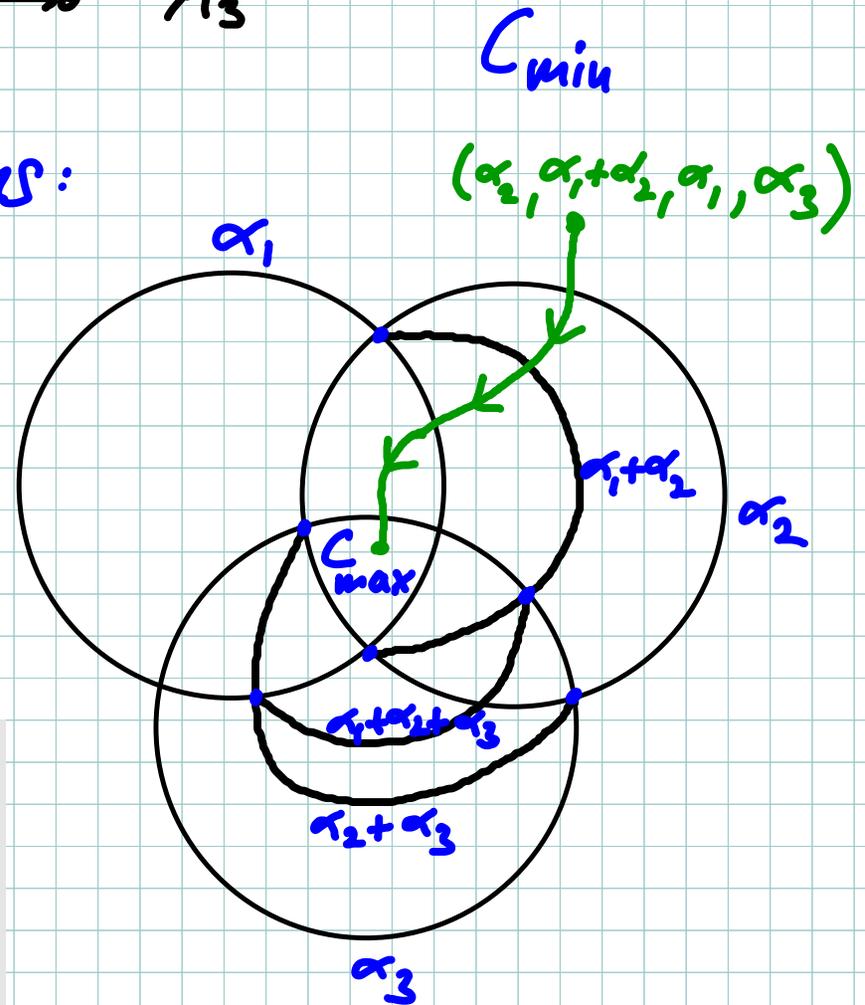
example: $Q = \overset{1}{\circ} \xrightarrow{2} \overset{2}{\circ} \xrightarrow{3} \overset{3}{\circ} \quad A_3$

Space of stability functions:

14 = Cat(4) chambers

9 MGS

lengths $3 \leq l \leq 6$



MGS = maximal chain

2) Basic Questions on MGS:

a) Existence, Finiteness

b) (per)mutations

c) Relevance

2) Basic Questions on MGS: c) Relevance

c.1) Reineke, Keller:

{MGS's for Q } \mapsto Quantum dilogarithm identities

$Q = \begin{smallmatrix} \circ & \xrightarrow{2} & \circ \\ & & \circ \end{smallmatrix}$ 2 MGS (α_1, α_2) and $(\alpha_2, \alpha_1 + \alpha_2, \alpha_1)$ yield:

Theorem 1.2 (Schützenberger [62], Faddeev-Volkov [16], Faddeev-Kashaev [17]).
For two indeterminates y_1 and y_2 which q -commute in the sense that

$$y_1 y_2 = q y_2 y_1,$$

we have the equality

$$\mathbb{E}(y_1) \mathbb{E}(y_2) = \mathbb{E}(y_2) \mathbb{E}(q^{-1/2} y_1 y_2) \mathbb{E}(y_1). \quad (1.3)$$

As shown in [17], this equality implies the classical 'pentagon identity' for Rogers' dilogarithm.

2) Basic Questions on MGS: c) Relevance

c.2) Quantum Field Theory

[Alim, Cecotti, Córdova, Espahbodi, Rastogi, Vafa, ...]

MGS \mapsto Spectrum of BPS particle

Show existence of MGS when Q is given by triangulation of a (non-closed) surface

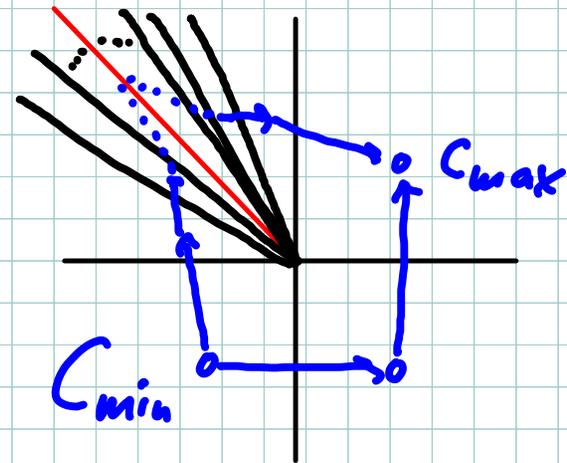
2) Basic Questions on MGS:

a) Existence, Finiteness

$$Q = \begin{matrix} & & 0 & \\ & \swarrow & & \searrow \\ 0 & & & 0 \end{matrix}$$

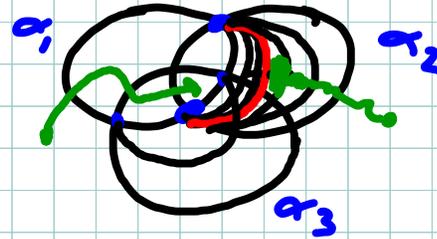
space of stability functions:

1 MGS (α_1, α_2)



$$Q = \begin{matrix} & & 3 & \\ & \swarrow & & \searrow \\ 1 & & 0 & \\ & \swarrow & & \searrow \\ & & 2 & \end{matrix}$$

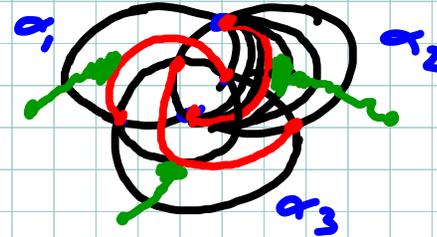
stability space



$0 < \# \text{MGS} < \infty$

$$Q = \begin{matrix} & & 3 & \\ & \swarrow & & \searrow \\ 1 & & 0 & \\ & \swarrow & & \searrow \\ & & 2 & \end{matrix}$$

stability space



0 MGS

2) Basic Questions on MGS:

a) Existence, Finiteness

Theorem: [BHIT]

Q mutation-equivalent to affine Dynkin quiver

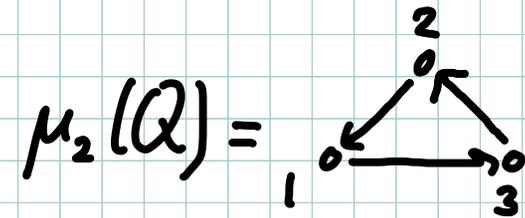
Then $0 < \# \text{MGS} < \infty$

2) Basic Questions on MGS:
↳ (per)mutations

example:

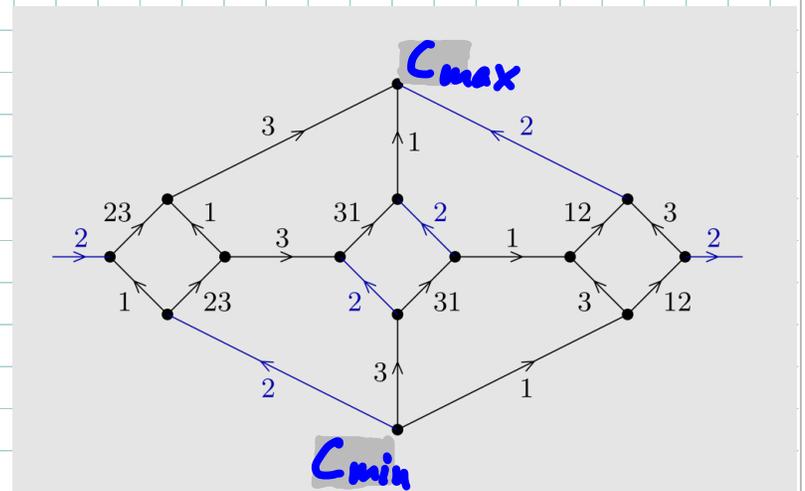
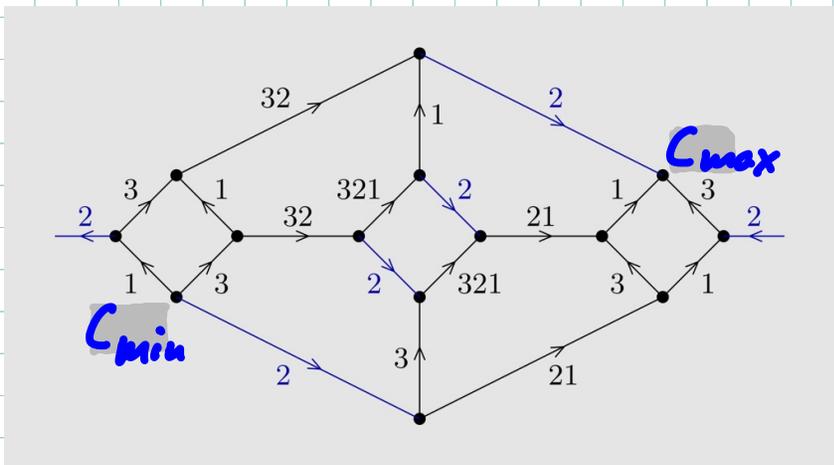


mutation
 $\xrightarrow{\mu_2}$

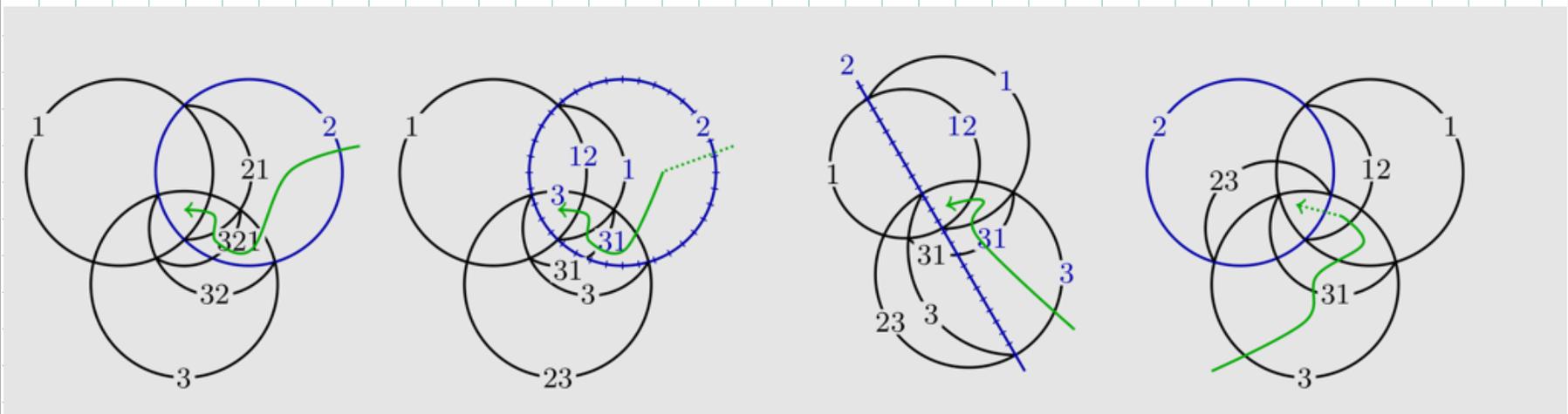
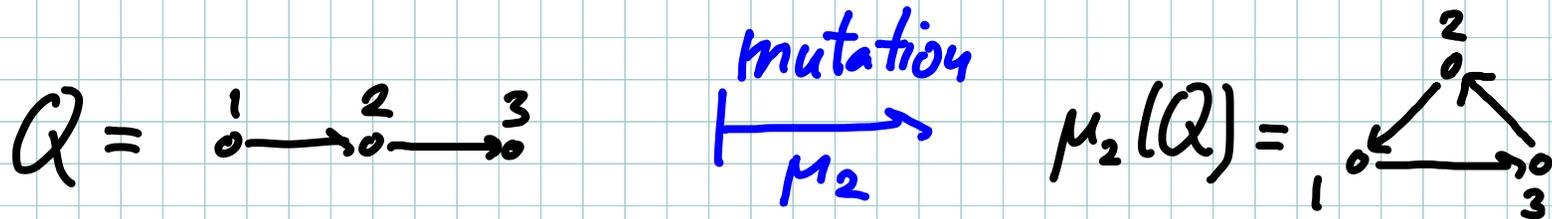


9 MGS
 lengths $3 \leq l \leq 6$

9 MGS
 lengths $4 \leq l \leq 5$



example:



$(2, 3, 321, 21, 1) \longrightarrow (3, 31, 1, 12, 2)$ *c-vectors*

$(2, 3, 1, 3, 1) \longrightarrow (3, 1, 3, 1, 2)$ *indices*

2) Basic Questions on MGS:

b) (per)mutations

Theorem: [BHIT] (Rotation Lemma)

Let $(\tau_0, \tau_1, \dots, \tau_m)$ be a MGS for Q , $1 \leq \tau_i \leq n$

Consider mutation $\mu_{\tau_0} : Q \mapsto \mu_{\tau_0}(Q)$.

Then $(\tau_1, \tau_2, \dots, \tau_m, \tau_{m+1})$ is MGS for $\mu_{\tau_0}(Q)$,
for a unique index τ_{m+1} .