# Base Size and Generic Stabilizers

Robert M. Guralnick

University of Southern California

Castle Hermonstceux - July 12, 2016

# G is a group acting on a set X of cardinality > 1 usually assume G is faithful (or reduce to that case)

A base for G on X is a subset B of X such that  $g \in G$  trivial on B implies g is trivial on X.

The *base size* is the minimal cardinality of a base. If *b* is small, then so is *G*.

Note that if |X| = n, then  $|G| \le b^n$ 

If X is a variety, then dim  $G \le b \dim X$ .

G is a group acting on a set X of cardinality > 1 usually assume G is faithful (or reduce to that case)

#### **Definition 1**

A base for G on X is a subset B of X such that  $g \in G$  trivial on B implies g is trivial on X.

The base size is the minimal cardinality of a base.

If b is small, then so is G.

Note that if |X| = n, then  $|G| \le b^n$ 

If X is a variety, then dim  $G \le b \dim X$ .

G is a group acting on a set X of cardinality > 1 usually assume G is faithful (or reduce to that case)

#### **Definition 1**

A base for G on X is a subset B of X such that  $g \in G$  trivial on B implies g is trivial on X.

The base size is the minimal cardinality of a base.

If b is small, then so is G.

Note that if |X| = n, then  $|G| \le b^n$ 

If X is a variety, then dim  $G \le b \dim X$ .

G is a group acting on a set X of cardinality > 1 usually assume G is faithful (or reduce to that case)

#### **Definition 1**

A base for G on X is a subset B of X such that  $g \in G$  trivial on B implies g is trivial on X.

The *base size* is the minimal cardinality of a base. If *b* is small, then so is *G*.

Note that if |X| = n, then  $|G| \le b^n$ 

If X is a variety, then dim  $G \le b \dim X$ .

It is a classical problem to determine base size. Examples:

- $\bigcirc$  b(GL(n,k)) = n
- ①  $b(PGL(n, k), Gr_d) = n/d + 2$

In the last case, we assume that 1 < d < n/2 and d divides n.

It is a classical problem to determine base size. Examples:

- $b(S_n) = n-1, b(A_n) = n-2$
- **2**b(GL(n,k)) = n
- $b(PGL(n, k), Gr_d) = n/d + 2$

In the last case, we assume that 1 < d < n/2 and d divides n.

It is a classical problem to determine base size. Examples:

- $b(S_n) = n-1, b(A_n) = n-2$
- $\bigcirc$  b(GL(n,k)) = n
- **3**  $b(PGL(n,k), Gr_d) = n/d + 2$

In the last case, we assume that 1 < d < n/2 and d divides n.

Based on results from several papers, we have:

#### Theorem 2

If G is a finite simple group acting primitively on X, then either the action is "standard" or  $b \le 7$ .

There is one example of base size 7 but infinitely many of base size 6 (coming from algebraic groups).

A relatively recent approach – instead of producing a base, show most subsets of size *b* are a base. Used by

Cameron-Kantor to show the base size is 2 for  $G = S_n$  with n large and the action not standard.

Based on results from several papers, we have:

#### Theorem 2

If G is a finite simple group acting primitively on X, then either the action is "standard" or  $b \le 7$ .

There is one example of base size 7 but infinitely many of base size 6 (coming from algebraic groups).

A relatively recent approach – instead of producing a base, show most subsets of size *b* are a base. Used by

Cameron-Kantor to show the base size is 2 for  $G = S_n$  with n large and the action not standard.

Based on results from several papers, we have:

#### Theorem 2

If G is a finite simple group acting primitively on X, then either the action is "standard" or  $b \le 7$ .

There is one example of base size 7 but infinitely many of base size 6 (coming from algebraic groups).

A relatively recent approach – instead of producing a base, show most subsets of size *b* are a base. Used by

Cameron-Kantor to show the base size is 2 for  $G = S_n$  with n large and the action not standard.

Note that G has base size b on X if and only if G has a regular orbit on  $X^b$ .

Regular orbits come up in many situations – in particular in the k(GV) problem of Brauer.

Ongoing program to determine the base size for *G* almost simple acting primitively on *X*. Done in many cases by various authors.

From now on, we will assume G is a simple algebraic group and X is an irreducible variety. There is a close relation between the base size for the algebraic group and the base size for the finite simple groups of Lie type.

Note that G has base size b on X if and only if G has a regular orbit on  $X^b$ .

Regular orbits come up in many situations – in particular in the k(GV) problem of Brauer.

Ongoing program to determine the base size for *G* almost simple acting primitively on *X*. Done in many cases by various authors.

From now on, we will assume G is a simple algebraic group and X is an irreducible variety. There is a close relation between the base size for the algebraic group and the base size for the finite simple groups of Lie type.

Note that G has base size b on X if and only if G has a regular orbit on  $X^b$ .

Regular orbits come up in many situations – in particular in the k(GV) problem of Brauer.

Ongoing program to determine the base size for G almost simple acting primitively on X. Done in many cases by various authors.

From now on, we will assume G is a simple algebraic group and X is an irreducible variety. There is a close relation between the base size for the algebraic group and the base size for the finite simple groups of Lie type.

Note that G has base size b on X if and only if G has a regular orbit on  $X^b$ .

Regular orbits come up in many situations – in particular in the k(GV) problem of Brauer.

Ongoing program to determine the base size for G almost simple acting primitively on X. Done in many cases by various authors.

From now on, we will assume G is a simple algebraic group and X is an irreducible variety. There is a close relation between the base size for the algebraic group and the base size for the finite simple groups of Lie type.

- $\bigcirc$  X = G/H where H is a maximal closed subgroup of G.
- X is a (rational) irreducible finite dimensional G-module.

New invariants in addition to b;  $b^0$  is the smallest size where some (and so generic) stabilizer of  $b^0$  points is finite  $b^1$  is the smallest size where the generic stabilizer is trivial

Clearly  $b^0 \le b \le b^1$ .

Burness-Guralnick-Saxl have determined in almost all cases in case (1)  $b^0$ , b,  $b^1$ . Often they are all 2. We use the classification of maximal closed subgroups.

Example: Assume characteristic not 2,  $\tau$  an involution inverting a maximal torus T.  $H = C_G(\tau)$  and X = G/H. Then generically the stabilizer of two points is conjugate to T[2] (2-torsion in T). However, there always is a regular orbit on  $X^2$ .

- $\bullet$  X = G/H where H is a maximal closed subgroup of G.
- ② *X* is a (rational) irreducible finite dimensional *G*-module.

New invariants in addition to b;  $b^0$  is the smallest size where some (and so generic) stabilizer of  $b^0$  points is finite  $b^1$  is the smallest size where the generic stabilizer is trivial

Clearly  $b^0 \le b \le b^1$ .

Burness-Guralnick-Saxl have determined in almost all cases in case (1)  $b^0$ , b,  $b^1$ . Often they are all 2. We use the classification of maximal closed subgroups.

Example: Assume characteristic not 2,  $\tau$  an involution inverting a maximal torus T.  $H = C_G(\tau)$  and X = G/H. Then generically the stabilizer of two points is conjugate to T[2] (2-torsion in T). However, there always is a regular orbit on  $X^2$ .



- $\bullet$  X = G/H where H is a maximal closed subgroup of G.
- ② X is a (rational) irreducible finite dimensional *G*-module.

New invariants in addition to b;  $b^0$  is the smallest size where some (and so generic) stabilizer of  $b^0$  points is finite  $b^1$  is the smallest size where the generic stabilizer is trivial

Clearly  $b^0 \le b \le b^1$ .

Burness-Guralnick-Saxl have determined in almost all cases in case (1)  $b^0$ , b,  $b^1$ . Often they are all 2. We use the classification of maximal closed subgroups.

Example: Assume characteristic not 2,  $\tau$  an involution inverting a maximal torus T.  $H = C_G(\tau)$  and X = G/H. Then generically the stabilizer of two points is conjugate to T[2] (2-torsion in T). However, there always is a regular orbit on  $X^2$ .



- $\bullet$  X = G/H where H is a maximal closed subgroup of G.
- ② X is a (rational) irreducible finite dimensional *G*-module.

New invariants in addition to b;  $b^0$  is the smallest size where some (and so generic) stabilizer of  $b^0$  points is finite  $b^1$  is the smallest size where the generic stabilizer is trivial

Clearly  $b^0 \le b \le b^1$ .

Burness-Guralnick-Saxl have determined in almost all cases in case (1)  $b^0$ , b,  $b^1$ . Often they are all 2. We use the classification of maximal closed subgroups.

Example: Assume characteristic not 2,  $\tau$  an involution inverting a maximal torus T.  $H = C_G(\tau)$  and X = G/H. Then generically the stabilizer of two points is conjugate to T[2] (2-torsion in T). However, there always is a regular orbit on  $X^2$ .



- $\bullet$  X = G/H where H is a maximal closed subgroup of G.
- ② *X* is a (rational) irreducible finite dimensional *G*-module.

New invariants in addition to b;  $b^0$  is the smallest size where some (and so generic) stabilizer of  $b^0$  points is finite  $b^1$  is the smallest size where the generic stabilizer is trivial

Clearly  $b^0 \le b \le b^1$ .

Burness-Guralnick-Saxl have determined in almost all cases in case (1)  $b^0$ , b,  $b^1$ . Often they are all 2. We use the classification of maximal closed subgroups.

Example: Assume characteristic not 2,  $\tau$  an involution inverting a maximal torus T.  $H = C_G(\tau)$  and X = G/H. Then generically the stabilizer of two points is conjugate to T[2] (2-torsion in T). However, there always is a regular orbit on  $X^2$ .



- $\bullet$  X = G/H where H is a maximal closed subgroup of G.
- ② *X* is a (rational) irreducible finite dimensional *G*-module.

New invariants in addition to b;  $b^0$  is the smallest size where some (and so generic) stabilizer of  $b^0$  points is finite  $b^1$  is the smallest size where the generic stabilizer is trivial

Clearly  $b^0 \le b \le b^1$ .

Burness-Guralnick-Saxl have determined in almost all cases in case (1)  $b^0$ , b,  $b^1$ . Often they are all 2. We use the classification of maximal closed subgroups.

Example: Assume characteristic not 2,  $\tau$  an involution inverting a maximal torus T.  $H = C_G(\tau)$  and X = G/H. Then generically the stabilizer of two points is conjugate to T[2] (2-torsion in T). However, there always is a regular orbit on  $X^2$ .

- $\bullet$  X = G/H where H is a maximal closed subgroup of G.
- ② *X* is a (rational) irreducible finite dimensional *G*-module.

New invariants in addition to b;  $b^0$  is the smallest size where some (and so generic) stabilizer of  $b^0$  points is finite  $b^1$  is the smallest size where the generic stabilizer is trivial

Clearly  $b^0 \le b \le b^1$ .

Burness-Guralnick-Saxl have determined in almost all cases in case (1)  $b^0$ , b,  $b^1$ . Often they are all 2. We use the classification of maximal closed subgroups.

Example: Assume characteristic not 2,  $\tau$  an involution inverting a maximal torus T.  $H = C_G(\tau)$  and X = G/H. Then generically the stabilizer of two points is conjugate to T[2] (2-torsion in T). However, there always is a regular orbit on  $X^2$ .



Now we come to linear actions.

In char 0, studied by A. M. Popov, Vinberg, V. Popov, etc.

Richardson: If G is reductive and X is a smooth affine variety in characteristic 0, then generic stabilizers exist (i.e. there is an open sub variety where all point stabilizers are conjugate). Fails in positive characteristic.

Burness-G-Liebeck-Testerman: most of the time, generic stabilizers are trivial in all cases, generic stabilizers exist. Now we come to linear actions.

In char 0, studied by A. M. Popov, Vinberg, V. Popov, etc.

Richardson: If G is reductive and X is a smooth affine variety in characteristic 0, then generic stabilizers exist (i.e. there is an open sub variety where all point stabilizers are conjugate). Fails in positive characteristic.

Burness-G-Liebeck-Testerman: most of the time, generic stabilizers are trivial in all cases, generic stabilizers exist.

Main tool: try to show that for any  $g \in G$  of prime order (or unipotent in char 0), we have dim  $V^g + \dim g^G < \dim V$ .

For some applications, you want to know that  $G_x$  is generically trivial as a group scheme. This can be checked by considering the Lie algebra of G.

BGLT: if dim  $V > \dim G$ , then  $G_X$  is generically finite.

Main tool: try to show that for any  $g \in G$  of prime order (or unipotent in char 0), we have dim  $V^g + \dim g^G < \dim V$ .

For some applications, you want to know that  $G_x$  is generically trivial as a group scheme. This can be checked by considering the Lie algebra of G.

BGLT: if dim  $V > \dim G$ , then  $G_X$  is generically finite.

Main tool: try to show that for any  $g \in G$  of prime order (or unipotent in char 0), we have dim  $V^g + \dim g^G < \dim V$ .

For some applications, you want to know that  $G_x$  is generically trivial as a group scheme. This can be checked by considering the Lie algebra of G.

BGLT: if dim  $V > \dim G$ , then  $G_X$  is generically finite.

Main tool: try to show that for any  $g \in G$  of prime order (or unipotent in char 0), we have dim  $V^g + \dim g^G < \dim V$ .

For some applications, you want to know that  $G_x$  is generically trivial as a group scheme. This can be checked by considering the Lie algebra of G.

BGLT: if dim  $V > \dim G$ , then  $G_X$  is generically finite.

Main tool: try to show that for any  $g \in G$  of prime order (or unipotent in char 0), we have dim  $V^g + \dim g^G < \dim V$ .

For some applications, you want to know that  $G_x$  is generically trivial as a group scheme. This can be checked by considering the Lie algebra of G.

BGLT: if dim  $V > \dim G$ , then  $G_X$  is generically finite.

# Some examples:

- **1**  $SO_n, n \ge 7$  on  $L(2\lambda_1)$ , characteristic not 2
- Which is a spin module of dimension 128
  2
- 3  $SL_9$  on  $\wedge^3$
- $^{4}$   $SL_{8}$  on  $\wedge^{4}$
- a few more small dimensional examples

# Some examples:

- **3**  $SO_n$ ,  $n \ge 7$  on  $L(2\lambda_1)$ , characteristic not 2
- 4 HSpin<sub>16</sub> on the half spin module of dimension 128
- 3  $SL_9$  on  $\wedge^3$
- $^{4}$   $SL_{8}$  on  $\wedge^{4}$
- a few more small dimensional examples

# Some examples:

- **3**  $SO_n$ ,  $n \ge 7$  on  $L(2\lambda_1)$ , characteristic not 2
- 4 HSpin<sub>16</sub> on the half spin module of dimension 128
- 3  $SL_9$  on  $\wedge^3$
- 4  $SL_8$  on  $\wedge^4$
- a few more small dimensional examples

# Some examples:

- **1**  $SO_n$ ,  $n \ge 7$  on  $L(2\lambda_1)$ , characteristic not 2
- 4 HSpin<sub>16</sub> on the half spin module of dimension 128
- 3  $SL_9$  on  $\wedge^3$
- $\bigcirc$  SL<sub>8</sub> on  $\wedge^4$
- a few more small dimensional examples

# Some examples:

- **1**  $SO_n$ ,  $n \ge 7$  on  $L(2\lambda_1)$ , characteristic not 2
- 4 HSpin<sub>16</sub> on the half spin module of dimension 128
- 3  $SL_9$  on  $\wedge^3$
- $\bigcirc$  SL<sub>8</sub> on  $\wedge^4$
- a few more small dimensional examples

# Some examples:

- **3**  $SO_n$ ,  $n \ge 7$  on  $L(2\lambda_1)$ , characteristic not 2
- 4 HSpin<sub>16</sub> on the half spin module of dimension 128
- 3  $SL_9$  on  $\wedge^3$
- $\bigcirc$  SL<sub>8</sub> on  $\wedge^4$
- a few more small dimensional examples

### Some examples:

- **1**  $SO_n$ ,  $n \ge 7$  on  $L(2\lambda_1)$ , characteristic not 2
- 4 HSpin<sub>16</sub> on the half spin module of dimension 128
- 3  $SL_9$  on  $\wedge^3$
- $\bigcirc$  SL<sub>8</sub> on  $\wedge^4$
- a few more small dimensional examples

Many examples come from the Vinberg setup.

The cases where  $G_x$  is generically finite but nontrivial are quite interesting. This has been used by Bhargava (in char 0).

# Some examples:

- **③**  $SO_n$ ,  $n \ge 7$  on  $L(2\lambda_1)$ , characteristic not 2
- 4 HSpin<sub>16</sub> on the half spin module of dimension 128
- 3  $SL_9$  on  $\wedge^3$
- $\bigcirc$  SL<sub>8</sub> on  $\wedge^4$
- a few more small dimensional examples

Many examples come from the Vinberg setup.

For example, if  $G = SO_n$ , we consider  $SL_n$  acting on the symmetric square. A generic stabilizer is  $SO_n$  and so a generic stabilizer in  $SO_n$  on  $L(2\lambda_1)$  is the intersection of  $SO_n$  with a generic conjugate in  $SL_n$  – note that  $SO_n$  is the centralizer of an involution inverting a maximal torus. So a generic stabilizer is the 2-torsion in a maximal torus.

In positive characteristic, this is usually true. Two counterexamples:

- $\bullet$   $G = SL_4$  in characteristic 3 and dim V = 20;
- ②  $G = SL_n$  and  $V = L \otimes L^{(q)}$  or  $L^* \otimes L^{(q)}$  where L is the natural module and  $L^{(q)}$  is the Frobenius twist.

In positive characteristic, this is usually true. Two counterexamples:

- $\bullet$   $G = SL_4$  in characteristic 3 and dim V = 20;
- ②  $G = SL_n$  and  $V = L \otimes L^{(q)}$  or  $L^* \otimes L^{(q)}$  where L is the natural module and  $L^{(q)}$  is the Frobenius twist.

In positive characteristic, this is usually true. Two counterexamples:

- $\bullet$   $G = SL_4$  in characteristic 3 and dim V = 20;
- ②  $G = SL_n$  and  $V = L \otimes L^{(q)}$  or  $L^* \otimes L^{(q)}$  where L is the natural module and  $L^{(q)}$  is the Frobenius twist.

In positive characteristic, this is usually true. Two counterexamples:

- $\bullet$   $G = SL_4$  in characteristic 3 and dim V = 20;
- ②  $G = SL_n$  and  $V = L \otimes L^{(q)}$  or  $L^* \otimes L^{(q)}$  where L is the natural module and  $L^{(q)}$  is the Frobenius twist.

If G is a simple group of adjoint type of rank at least 2, then the essential dimension of G is at most d = 2 + 1.

- This was proved by Lemire in characteristic 0.
- 2. Without the -1 proved by Burness-G-Saxl (following a Reichstein suggestion).
- 3. As stated a result of Garibaldi-G (using BGS).

#### Theorem 3

If G is a simple group of adjoint type of rank at least 2, then the essential dimension of G is at most dim  $G - 2\operatorname{rank} G - 1$ .

- 1. This was proved by Lemire in characteristic 0.
- 2. Without the -1 proved by Burness-G-Saxl (following a Reichstein suggestion).
- As stated a result of Garibaldi-G (using BGS).

#### Theorem 3

If G is a simple group of adjoint type of rank at least 2, then the essential dimension of G is at most dim  $G - 2\operatorname{rank} G - 1$ .

- 1. This was proved by Lemire in characteristic 0.
- 2. Without the -1 proved by Burness-G-Saxl (following a Reichstein suggestion).
- As stated a result of Garibaldi-G (using BGS).

#### Theorem 3

If G is a simple group of adjoint type of rank at least 2, then the essential dimension of G is at most dim  $G - 2\operatorname{rank} G - 1$ .

- 1. This was proved by Lemire in characteristic 0.
- 2. Without the -1 proved by Burness-G-Saxl (following a Reichstein suggestion).
- 3. As stated a result of Garibaldi-G (using BGS).

It turns out for most simple algebraic groups over an algebraically closed field, the essential dimension is bounded above by dim G. The exception comes out of a beautiful result of Brosnan-Reichstein-Vistoli who give exponential lower bounds for Spin and Half Spin groups (in characteristic not 2) and essentially show in characteristic 0, the lower bounds are the right answer (for  $n \ge 15$ ).

In positive odd characteristic, this is also true. It follows from GG that for  $15 < n \ne 16$ , the half spin or spin groups act generically freely on the half spin or spin modules. This uses the inequality  $\operatorname{ed}(G) \le \dim X - \dim G$  where G acts generically freely on the variety X and the action is verbal (any linear module is verbal).

This gives an upper bound which equals the lower bound of BRV.

It turns out for most simple algebraic groups over an algebraically closed field, the essential dimension is bounded above by dim G. The exception comes out of a beautiful result of Brosnan-Reichstein-Vistoli who give exponential lower bounds for Spin and Half Spin groups (in characteristic not 2) and essentially show in characteristic 0, the lower bounds are the right answer (for  $n \ge 15$ ).

In positive odd characteristic, this is also true. It follows from GG that for  $15 < n \ne 16$ , the half spin or spin groups act generically freely on the half spin or spin modules. This uses the inequality  $\operatorname{ed}(G) \le \dim X - \dim G$  where G acts generically freely on the variety X and the action is verbal (any linear module is verbal).

This gives an upper bound which equals the lower bound of BRV.

Another application of generic stabilizers: stabilizers of homogeneous polynomials.

## Theorem 4

Let H be a simple algebraic group with V an irreducible module. Suppose that  $H < G \le SL(V)$ . Then with a small number of exceptions,  $k[V]^G$  has smaller transcendency degree than  $k[V]^H$ .

This implies that for almost all  $f \in k[V]^H$ , H is the connected component of the stabilizer in GL(V) of f.

A very special case is a 125 year old question of Cartan (new even over  $\mathbb{C}$ ).

Let f be the degree 8 invariant of  $E_8(k)$  acting on its Lie algebra. Then the stabilizer in GL(V) of f is just  $\mu_8 \times E_8(k)$ .

Another application of generic stabilizers: stabilizers of homogeneous polynomials.

## Theorem 4

Let H be a simple algebraic group with V an irreducible module. Suppose that  $H < G \le SL(V)$ . Then with a small number of exceptions,  $k[V]^G$  has smaller transcendency degree than  $k[V]^H$ .

This implies that for almost all  $f \in k[V]^H$ , H is the connected component of the stabilizer in GL(V) of f.

A very special case is a 125 year old question of Cartan (new even over  $\mathbb{C}$ ).

Let f be the degree 8 invariant of  $E_8(k)$  acting on its Lie algebra. Then the stabilizer in GL(V) of f is just  $\mu_8 \times E_8(k)$ .

Another application of generic stabilizers: stabilizers of homogeneous polynomials.

## Theorem 4

Let H be a simple algebraic group with V an irreducible module. Suppose that  $H < G \le SL(V)$ . Then with a small number of exceptions,  $k[V]^G$  has smaller transcendency degree than  $k[V]^H$ .

This implies that for almost all  $f \in k[V]^H$ , H is the connected component of the stabilizer in GL(V) of f.

A very special case is a 125 year old question of Cartan (new even over  $\mathbb{C}$ ).

Let f be the degree 8 invariant of  $E_8(k)$  acting on its Lie algebra. Then the stabilizer in GL(V) of f is just  $\mu_8 \times E_8(k)$ .