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4 Elimination Theory

Elimination theory reduces a system of polynomial equations in many variables to systems in a smaller number of variables. From a geometric perspective, these methods lead to the equations for closures of the image of a rational map.

4.0 Implicitization

How is implicitization related to elimination?

4.0.0 Proposition (Polynomial implicitization). Let \mathbb{K} be an infinite field and let $X := V(f_1, f_2, ..., f_r)$ be an affine subvariety in \mathbb{A}^n . For any polynomial map $\rho: X \to \mathbb{A}^m$, consider the ideal

$$I := \langle y_1 - \rho_1, y_2 - \rho_2, \dots, y_m - \rho_m, f_1, f_2, \dots, f_r \rangle$$

in the polynomial ring $\mathbb{K}[x_1, x_2, ..., x_n, y_1, y_2, ..., y_m]$. The Zariski closure of the image $\rho(X)$ is $\mathbb{V}(I \cap \mathbb{K}[y_1, y_2, ..., y_m])$.

Proof. Let $Z = V(I) \subseteq \mathbb{A}^{n+m}$ and set $J := I \cap \mathbb{K}[y_1, y_2, ..., y_m]$. Choose an algebraic closure \mathbb{K} of the field \mathbb{K} . When $\mathbb{K} = \mathbb{K}$, the Closure Theorem 3.2.5 establishes that V(J) is the smallest affine subvariety containing the image $\rho(X) = \pi_2(Z)$ where $\pi_2 \colon \mathbb{A}^{n+m} \to \mathbb{A}^m$ is defined by $(x_1, x_2, ..., x_n, y_1, y_2, ..., y_m) \mapsto (y_1, y_2, ..., y_m)$. When $\mathbb{K} \neq \mathbb{K}$, we cannot apply the closure theorem directly. Since the algorithm, that returns the elimination ideal, is unaffected by the underlying field, passing to the larger field does not change the ideal *J*. We prove that $V_{\mathbb{K}}(J)$ is the smallest affine variety in $\mathbb{A}^m(\mathbb{K})$ containing $\rho(X)$.

We first claim that $\rho(X) = \pi_2(Z) \subseteq V_{\mathbb{K}}(J)$. Fix $f \in J$. For each point $a \in \pi_2(X)$, choose a point $b = (b_1, b_2, \dots, b_n, a_1, a_2, \dots, a_m) \in Z$ such that $\pi_2(b) = a$. We have $f(a) = \pi_2^*(f(b)) = 0$. This shows that the polynomial f vanishes at all points in $\pi_2(Z)$.

Let $Y(\mathbb{K}) = V_{\mathbb{K}}(g_1, g_2, ..., g_s) \subseteq \mathbb{A}^m(\mathbb{K})$ be any affine subvariety such that $\rho(X(\mathbb{K})) \subseteq Y(\mathbb{K})$. We must show $V_{\mathbb{K}}(J) \subseteq Y(\mathbb{K})$. Observe that each g_i vanishes on $Y(\mathbb{K})$, so it also vanishes on the smaller set $\rho(X(\mathbb{K}))$. This shows that each $g_i \circ \rho$ vanishes on $\mathbb{A}^m(\mathbb{K})$. Since \mathbb{K} is infinite, we see that $g_i \circ \rho$ is the zero polynomial and vanishes on $\mathbb{A}^m(\overline{\mathbb{K}})$. Hence, each g_i vanishes on $\rho(X(\overline{\mathbb{K}}))$. We deduce that $\rho(X(\overline{\mathbb{K}})) \subseteq Y(\overline{\mathbb{K}}) = V_{\overline{\mathbb{K}}}(g_1, g_2, ..., g_s) \subseteq \mathbb{A}^m(\overline{\mathbb{K}})$. Since the theorem is true over $\overline{\mathbb{K}}$, it follows that $V_{\overline{\mathbb{K}}}(J) \subseteq Y(\overline{\mathbb{K}})$. Concentrating on the points that lie in $\mathbb{A}^m(\mathbb{K})$, we conclude that $V_{\mathbb{K}}(J) \subseteq Y(\mathbb{K})$. We use a subscript to keep track of the field, so $V_{\mathbb{K}}(J)$ is the affine subvariety in $\mathbb{A}^m(\mathbb{K})$ and $V_{\overline{\mathbb{K}}}(J)$ is the larger set in $\mathbb{A}^m(\overline{\mathbb{K}})$.

4.0.1 Example. Let *m* be a positive integers. The affine cone over the *rational normal curve* of degree *m* is the closure of image of the map $\rho: \mathbb{A}^2 \to \mathbb{A}^{m+1}$ defined by $(x_1, x_2) \mapsto (x_1^m, x_1^{m-1}x_2, x_1^{m-2}x_2^2, \dots, x_2^m)$. Its ideal is generated by the 2-minors of the Hankel $(2 \times m)$ -matrix

	x_1^{m-1}	$x_1^{m-2}x_2$	•••	x_2^{m-1}
x_1	<i>y</i> ₁	y_2	• • •	y_m
x_2	y2	<i>Y</i> 3	• • •	y_{m+1}] ·

For instance, when m = 3, the Gröbner basis with respect to the lexicographic order of $\langle y_1 - x_1^3, y_2 - x_1^2 x_2, y_3 - x_1 x_2^3, y_4 - x_2^3 \rangle$ is

so closure of the image is cut out by the 2-minors of $\begin{bmatrix} y_1 & y_2 & y_3 \\ y_2 & y_3 & y_4 \end{bmatrix}$.

4.0.2 Remark. The cone over the rational curve of degree 3 in \mathbb{A}^4 is $X := V(y_3^2 - y_2y_4, y_2y_3 - y_1y_4, y_2^2 - y_1y_3)$. All three equations are needed to obtain an irreducible variety. The affine subvariety cut out by any two equations is a union:

$$\begin{split} & \mathsf{V}(y_2^2 - y_1 y_3, y_2 y_3 - y_1 y_4) = \mathsf{X} \cup \mathsf{V}(y_1, y_2) \,, \\ & \mathsf{V}(y_3^2 - y_2 y_4, y_2 y_3 - y_1 y_4) = \mathsf{X} \cup \mathsf{V}(y_3, y_4) \,, \\ & \mathsf{V}(y_3^2 - y_2 y_4, y_2^2 - y_1 y_3) = \mathsf{X} \cup \mathsf{V}(y_2, y_3) \,. \end{split}$$

4.0.3 Example. For any two positive integers *n* and *m*, the *Segre embedding* is the map $\sigma_{n,m} \colon \mathbb{A}^n \times \mathbb{A}^m \to \mathbb{A}^{nm}$ defined by

 $(x_1, x_2, \ldots, x_n, y_1, y_2, \ldots, x_m) \mapsto (x_1y_1, x_1y_2, \ldots, x_1y_m, x_2y_1, x_2y_2, \ldots, x_2y_m, \ldots, x_ny_1, x_ny_2, \ldots, x_ny_m).$

Its ideal is generated by the 2-minors of the generic $(n \times m)$ -matrix

	<u>y</u> 1	<i>Y</i> 2	•••	y_m		
x_1	z_1	z_2	• • •	z_m		
x_2	z_{m+1}	z_{m+2}	• • •	z_{2m}		
:		:		:	•	\diamond
x_n	$z_{(n-1)m+1}$	$z_{(n-1)m+2}$	• • •	z_{nm}		

image of the Segre map generated by quadratic polynomial $z_1 z_4 - z_2 z_3$.

When n = m = 2, the ideal for the

4.0.4 Example. For any positive integer *n* and *d*, set $m := \binom{d+n-1}{d}$. The *Veronese* (or *d-uple*) embedding is the map $v_d : \mathbb{A}^n \to \mathbb{A}^m$ defined by $(x_1, x_2, \ldots, x_n) \mapsto (x_1^d, x_1^{d-1}x_2, \ldots, x_n^d)$. Its ideal is generated by the 2-minors of a catalecticant $(n \times \binom{d+n-2}{d-1})$ -matrix. When (n, d) equals (3, 2) or (3, 3), the matrices are

This map is named after Giuseppe Veronese, an Italian mathematician who worked on the geometry of multidimensional spaces.

This affine subvariety is a cone because it contains all lines joining the point (0, 0, ..., 0) with a point on the curve parametrized by $x_2 \mapsto (1, x_2, ..., x_2^m)$.

This map is named after Corrado Segre, an Italian mathematician responsible for important early work in algebraic geometry.

4.1 Toric Ideals

How do we solve the rational implicitization problem?

4.1.0 Theorem (Rational implicitization). Let \mathbb{K} be an infinite field and let $\rho: \mathbb{A}^n \dashrightarrow \mathbb{A}^m$ be a rational map where $\rho_j = f_j/g_j$ for all $1 \le j \le m$. Consider the ideal

$$I = \langle g_1 y_1 - f_1, g_2 y_2 - f_2, \dots, g_m y_m - f_m, g_1 g_2 \cdots g_m z - 1 \rangle$$

in the ring $\mathbb{K}[z, x_1, x_2, \dots, x_n, y_1, y_2, \dots, y_m]$. The Zariski closure of the image $\rho(\mathbb{A}^n)$ is $\mathbb{V}(I \cap \mathbb{K}[y_1, y_2, \dots, y_m])$.

Proof. By setting $g := g_1 g_2 \cdots g_m$, we see that the rational map ρ is well-defined over the open set $U = \{a \in \mathbb{A}^n \mid g(a) \neq 0\}$. Consider the affine subvariety $Y := V(zg-1) \subset \mathbb{A}^{n+1}$ and the projection map $\pi : \mathbb{A}^{n+1} \to \mathbb{A}^n$ defined by $(z, x_1, x_2, \dots, x_n) \mapsto (x_1, x_2, \dots, x_n)$. The map π is a birational morphism: the rational map $\psi : \mathbb{A}^n \dashrightarrow Y$ defined by $(x_1, x_2, \dots, x_n) \mapsto (1/g, x_1, x_2, \dots, x_n)$ satisfies both $\pi \circ \psi = \mathrm{id}_U$ and $\psi \circ \pi = \mathrm{id}_Y$. Moreover, the morphism $\phi : Y \to \mathbb{A}^m$ defined by

$$(z, x_1, x_2, \dots, x_n) \mapsto (f_1 g_2 \cdots g_m z, g_1 f_2 g_3 \cdots g_m z, \dots, g_1 \cdots g_{m-1} f_m z)$$

satisfies $\phi = \rho \circ \pi$. Thus, we have $\phi(Y) = \rho(U)$ and the result follows from the polynomial implicitization theorem.

4.1.1 Problem. Consider the rational map $\rho \colon \mathbb{A}^1 \dashrightarrow \mathbb{A}^2$ defined, for all $t \in \mathbb{A}^1$, by $t \mapsto \left(\frac{1-t^2}{1+t^2}, \frac{2t}{1+t^2}\right)$. Find the Zariski closure of its image.

Solution. The reduced Gröbner basis, with respect to >_{lex}, for the ideal $\langle (1 + t^2)y_1 - (1 - t^2), (1 + t^2)y_2 - 2t, 1 - (1 + t^2)z \rangle$ in the ring $\mathbb{K}[z, t, y_1, y_2]$ is $y_1^2 + y_2^2 - 1, ty_2 + y_1 - 1, ty_1 + t - y_2, 2z - y_1 - 1$, so the closure of the image is the unit circle.

4.1.2 Definition (Toric ideals). Fix an integer matrix $\mathbf{A} \in \mathbb{Z}^{d \times n}$ with columns $\mathbf{a}_1, \mathbf{a}_2, \ldots, \mathbf{a}_n \in \mathbb{Z}^d$. The affine toric variety $X_{\mathbf{A}}$ associated to the matrix \mathbf{A} is the Zariski closure of the image of the rational map $\rho_{\mathbf{A}} \colon \mathbb{A}^d \dashrightarrow \mathbb{A}^n$ where $(x_1, x_2, \ldots, x_d) \mapsto (x^{\mathbf{a}_1}, x^{\mathbf{a}_2}, \ldots, x^{\mathbf{a}_n})$.

4.1.3 Examples. The cone over the rational normal curve of degree *m*, the Veronese embedding $\nu_2 \colon \mathbb{A}^3 \to \mathbb{A}^6$, and the Segre embedding $\sigma_{2,2} \colon \mathbb{A}^2 \times \mathbb{A}^2 \to \mathbb{A}^4$ correspond to the matrices

$$\begin{bmatrix} m & m-1 & m-2 & \cdots & 1 & 0 \\ 0 & 1 & 2 & \cdots & m-1 & m \end{bmatrix}, \begin{bmatrix} 2 & 1 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 2 & 1 & 0 \\ 0 & 0 & 1 & 0 & 1 & 2 \end{bmatrix}, \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{bmatrix}$$

respectively.

The graph of a rational map may not be an affine subvariety.

4.1.4 Remark. The rational map $\rho_{\mathbf{A}} \colon \mathbb{A}^d \dashrightarrow \mathbb{A}^n$ corresponds to the ring map $\varphi_{\mathbf{A}} \colon \mathbb{K}[y_1, y_2, \dots, y_n] \to \mathbb{K}[x_1^{\pm 1}, x_2^{\pm 1}, \dots, x_d^{\pm 1}]$ defined, for all $1 \leq i \leq n$, by $y_i \mapsto x^{a_i}$. The *toric ideal* $I_{\mathbf{A}}$ in the ring $\mathbb{K}[y_1, y_2, \dots, y_n]$ associated to the matrix \mathbf{A} is Ker $\varphi_{\mathbf{A}}$. The rational implicitization theorem implies that $X_{\mathbf{A}} = \mathcal{V}(\text{Ker } \varphi_{\mathbf{A}})$.

4.1.5 Lemma. Let \mathbf{A} be an integer $(d \times n)$ -matrix. The toric ideal $I_{\mathbf{A}}$ in the ring $\mathbb{K}[y_1, y_2, \dots, y_n]$ is spanned as a \mathbb{K} -vector space by the set of binomials $\{y^{\mathbf{u}} - y^{\mathbf{v}} \mid \text{for all } u, v \in \mathbb{N}^n \text{ satisfying } \mathbf{A} \mathbf{u} = \mathbf{A} \mathbf{v}\}.$

Proof. A binomial $y^{\mathbf{u}} - y^{\mathbf{v}}$ lies in the ideal $I_{\mathbf{A}}$ if and only if we have $\mathbf{A} \mathbf{u} = \mathbf{A} \mathbf{v}$. Thus, it suffices to show that each polynomial in $I_{\mathbf{A}}$ is a K-linear combination of these binomials. Fix a monomial order on the polynomial ring $\mathbb{K}[y_1, y_2, \dots, y_n]$. Suppose $f \in I_{\mathbf{A}}$ cannot be written as a K-linear combination of the binomials. Choose f with this property such that $\mathrm{LT}(f) = y^{\mathbf{u}}$ is minimal with respect to the monomial order. When expanding $f \circ \varphi_{\mathbf{A}} = f(x^{\mathbf{a}_1}, x^{\mathbf{a}_2}, \dots, x^{\mathbf{a}_n})$, we obtain the zero polynomial. The term $x^{\mathbf{A} \mathbf{u}}$ in f must cancel out. Hence, there is some other monomial $x^{\mathbf{v}} < x^{\mathbf{u}}$ appearing in f such that $\mathbf{A} \mathbf{u} = \mathbf{A} \mathbf{v}$. The polynomial $f' = f - x^{\mathbf{u}} + x^{\mathbf{v}}$ cannot be written as a K-linear combination of binomials in $I_{\mathbf{A}}$. Since $\mathrm{LT}(f') < \mathrm{LT}(f)$, we have a contradiction.

4.1.6 Remark. Any vector $\mathbf{u} \in \mathbb{Z}^n$ can be expressed uniquely in the form $\mathbf{u} = \mathbf{u}^+ - \mathbf{u}^-$ where the vectors \mathbf{u}^+ and \mathbf{u}^- are nonnegative and have disjoint support. More precisely, the *i*-th coordinate in \mathbf{u}^+ equals u_i if $u_i > 0$ and equals 0 otherwise. Let Ker A denote the sublattice of \mathbb{Z}^n consisting of all vectors \mathbf{u} such that $\mathbf{A} \mathbf{u}^+ = \mathbf{A} \mathbf{u}^-$.

4.1.7 Corollary. Let **A** be an integer matrix. The toric ideal $I_{\mathbf{A}}$ in the ring $\mathbb{K}[y_1, y_2, \dots, y_n]$ is generated by $y^{\mathbf{u}^+} - y^{\mathbf{u}^-}$ where $\mathbf{u} \in \text{Ker } \mathbf{A}$. \Box

4.1.8 Corollary. Let **A** be an integer matrix. For any monomial order > on the polynomial ring $\mathbb{K}[y_1, y_2, \ldots, y_n]$, there is a finite set of vectors $\mathcal{G} \subset \text{Ker } \mathbf{A}$ such that the reduced Gröbner basis of the toric ideal $I_{\mathbf{A}}$ with respect to > is equal to $\{y^{\mathbf{u}^+} - y^{\mathbf{u}^-} \mid \mathbf{u} \in \mathcal{G}\}$.

Proof. By combining the Hilbert Basis Theorem and Corollary 4.1.7, there is a finite subset of Ker **A** such that the associated binomials generate the toric ideal $I_{\mathbf{A}}$. Apply the Buchberger Algorithm to these binomials to find a Gröbner basis of this ideal. The construction of S-polynomials and the reduction steps preserve the binomial structure. Therefore, any polynomial arising during this process lies in the set $\{y^{\mathbf{u}^+} - y^{\mathbf{u}^-} \mid \mathbf{u} \in \operatorname{Ker} \mathbf{A}\}$.

4.2 Common Roots

When does a system of polynomial equations have solutions? We need a criteria to understand how to solve the extension problem.

To introduce the concept of a resultant, we examine when two polynomials in $\mathbb{K}[x]$ have a common factor.

4.2.0 Lemma. Let f and g be polynomials in $\mathbb{K}[x]$ of positive degrees ℓ and m respectively. The polynomials f and g have a common factor if and only *if there exists nonzero polynomials p and q in* $\mathbb{K}[x]$ such that deg p < m, deg $q < \ell$, and p f + q g = 0.

Proof. Assume that f and g have a common factor h. Hence, there exists \hat{f} and \hat{g} in $\mathbb{K}[x]$ such that deg $\hat{f} < \ell$, $f = h\hat{f}$, deg $\hat{g} < m$, and $g = h\hat{g}$. It follows that $\hat{g}f + (-\hat{f})g = \hat{g}h\hat{f} - \hat{f}h\hat{g} = 0$.

Assume that *p* and *q* have the desired properties. Suppose that *f* and *g* have no common factor, so their greatest common divisor is 1. Hence, there exists *a* and *b* in $\mathbb{K}[x]$ such that af + bg = 1. Multiplying this equation by *q* and using the relation qg = -pf, we obtain q = (af + bg)q = aqf - bpf = (aq - bp)f. Since *q* is nonzero, we deduce that *q* has degree at least ℓ which contradicts the second condition. Thus, there must be a common factor.

4.2.1 Remark. This lemma allows one to use linear algebra to determine if *f* and *g* have a common factor. The idea is to turn polynomial equation p f + q g = 0 into a system of linear equations. Let

$$f = a_{\ell} x^{\ell} + a_{\ell-1} x^{\ell-1} + \dots + a_0 \qquad p = c_{m-1} x^{m-1} + c_{m-2} x^{m-2} + \dots + c_0 g = b_m x^m + b_{m-1} x^{m-1} + \dots + b_0 \qquad q = d_{\ell-1} x^{\ell-1} + d_{\ell-2} x^{\ell-2} + \dots + d_0$$

where we regard the coefficients as unknowns. Substituting into the equation p f + q g = 0 and comparing the coefficients of powers of x, we obtain a homogeneous system of linear equations:

$$\begin{array}{rcrcrcrc} a_{\ell}c_{m-1} & + & b_{m}d_{\ell-1} & = & 0 & \text{coefficient of } x^{\ell+m-1} \\ a_{\ell-1}c_{m-1} + a_{\ell}c_{m-2} & + & b_{m-1}d_{\ell-1} + b_{m}d_{\ell-2} & = & 0 & \text{coefficient of } x^{\ell+m-1} \\ & & & \ddots & & & \vdots \\ a_{0}c_{0} & + & b_{0}d_{0} & = & 0 & \text{coefficient of } x^{0} \\ \end{array}$$

$$\Rightarrow \quad \begin{bmatrix} a_{\ell} & b_{m} \\ \vdots & \ddots & \vdots & \ddots \\ \vdots & a_{\ell} & \vdots & b_{m} \\ a_{0} & \vdots & b_{0} & \vdots \\ & \ddots & \vdots & \ddots & \vdots \\ & a_{0} & & b_{0} \end{bmatrix} \begin{bmatrix} c_{m-1} \\ \vdots \\ c_{0} \\ d_{\ell-1} \\ \vdots \\ d_{0} \end{bmatrix} = \begin{bmatrix} 0 \\ \vdots \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

We know from linear algebra that there is a nonzero solution if and only if the coefficient matrix has zero determinant. **4.2.2 Definition.** Given *f* and *g* in $\mathbb{K}[x]$ of positive degree, we write $f = a_{\ell} x^{\ell} + a_{\ell-1} x^{\ell-1} + \cdots + a_0$ and $g = b_m x^m + b_{m-1} x^{m-1} + \cdots + b_0$ where $a_{\ell} \neq 0$ and $b_m \neq 0$. The *resultant* of *f* and *g* with respect to *x* is the determinant of the following $((\ell + m) \times (\ell + m))$ -matrix

$$\operatorname{Syl}(f,g;x) := \begin{bmatrix} a_{\ell} & a_{\ell-1} & a_{\ell-2} & \cdots & a_1 & a_0 & 0 & 0 & \cdots & 0 \\ 0 & a_{\ell} & a_{\ell-1} & \cdots & a_2 & a_1 & a_0 & 0 & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & a_{\ell} & a_{\ell-1} & a_{\ell-2} & a_{\ell-3} & \cdots & a_0 \\ b_m & b_{m-1} & b_{m-2} & \cdots & b_1 & b_0 & 0 & 0 & \cdots & 0 \\ 0 & b_m & b_{m-1} & \cdots & b_2 & b_1 & b_0 & 0 & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & b_m & b_{m-1} & b_{m-2} & b_{m-3} & \cdots & b_0 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ \vdots \\ m \\ m+1 \\ m+2 \\ \vdots \\ m+\ell \end{bmatrix}$$

Set $\operatorname{Res}(f, g; x) := \operatorname{det} \operatorname{Syl}(f, g, x)$.

4.2.3 Proposition. Given two f and g in $\mathbb{K}[x]$ having positive degree, the resultant $\operatorname{Res}(f,g;x)$ lies in $\mathbb{Z}[a_0,a_1,\ldots,a_\ell,b_0,b_1,\ldots,b_m]$. These two polynomials f and g have a common factor if and only if $\operatorname{Res}(f,g;x) = 0$.

Proof. For any $(n \times n)$ -matrix $\mathbf{A} = [a_{j,k}]$, the standard formula for the determinant is $\det(A) = \sum_{\sigma \in \mathfrak{S}_n} \operatorname{sgn}(\sigma) a_{1,\sigma(1)} a_{2,\sigma(2)} \cdots a_{n,\sigma(n)}$, which is an integer polynomial in its entries proving the first assertion. The second assertion follows from the preceding remark.

4.2.4 Examples. We have $gcd(2x^2 + 3x + 1, 7x^2 + x + 3) = 1$ because $Res(2x^2 + 3x + 1, 7x^2 + x + 3; x) = det \begin{bmatrix} 1 & 3 & 2 & 0 \\ 0 & 1 & 3 & 2 \\ 3 & 1 & 7 & 0 \\ 0 & 3 & 1 & 7 \end{bmatrix} = 153 \neq 0.$

Two linear polynomials have a common factor if and only if they span the same 1-dimensional space;

$$\operatorname{Res}(a_1 x + a_0, b_1 x + b_0; x) = \operatorname{det} \begin{bmatrix} a_1 & a_0 \\ b_1 & b_0 \end{bmatrix} = a_1 b_0 - a_0 b_1.$$

Since

$$\operatorname{Res}(a_2 x^2 + a_1 x + a_0, 2a_2 x + a_1; x) = \operatorname{det} \begin{bmatrix} a_2 & a_1 & a_0 \\ 2a_2 & a_1 & 0 \\ 0 & 2a_2 & a_1 \end{bmatrix} = -a_2(a_1^2 - 4a_0 a_2),$$

the quadratic polynomial $a_2 x^2 + a_1 x + a_0$ has a double root if and only if we have $a_1^2 - 4 a_0 a_2 = 0$. Similarly, the cubic polynomial $a_3 x^3 + a_2 x^2 + a_1 x + a_0$ has a multiple root if and only we have

$$\operatorname{Res}(a_{3} x^{3} + a_{2} x^{2} + a_{1} x + a_{0}, 3a_{3} x^{2} + 2a_{2} x + a_{1}; x)$$

$$= \operatorname{det} \begin{bmatrix} a_{3} & a_{2} & a_{1} & a_{0} & 0 \\ 0 & a_{3} & a_{2} & a_{1} & a_{0} \\ 3a_{3} & 2a_{2} & a_{1} & 0 & 0 \\ 0 & 3a_{3} & 2a_{2} & a_{1} & 0 \\ 0 & 0 & 3a_{3} & 2a_{2} & a_{1} \end{bmatrix}$$

$$= a_{3}(27a_{0}^{2}a_{3}^{2} + 4a_{0}a_{2}^{3} + 4a_{1}^{3}a_{3} - a_{1}^{2}a_{2}^{2} - 18a_{0}a_{1}a_{2}a_{3}) = 0.$$

This matrices are named after James Sylvester who did important work on matrix theory.