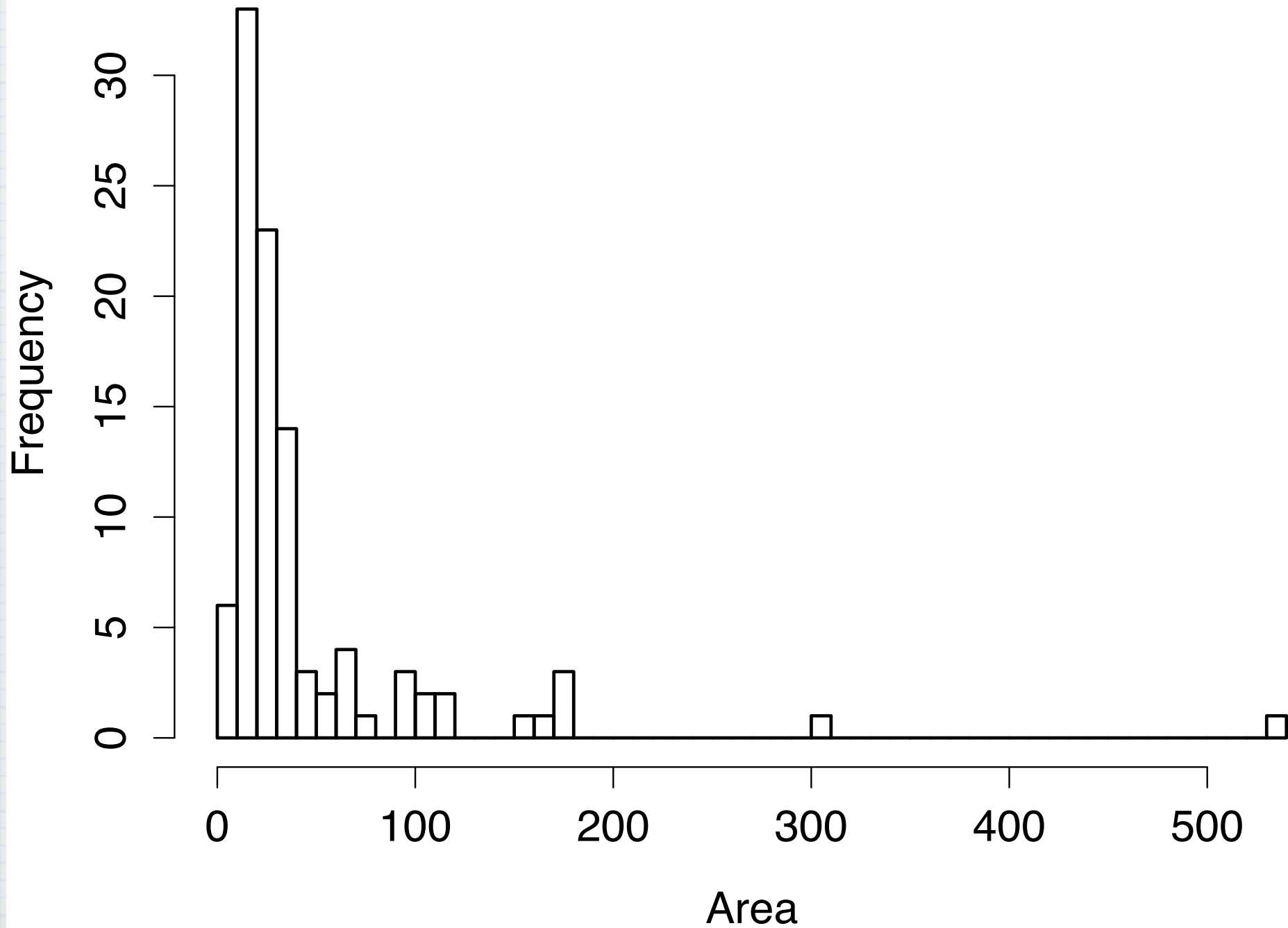


Sampling

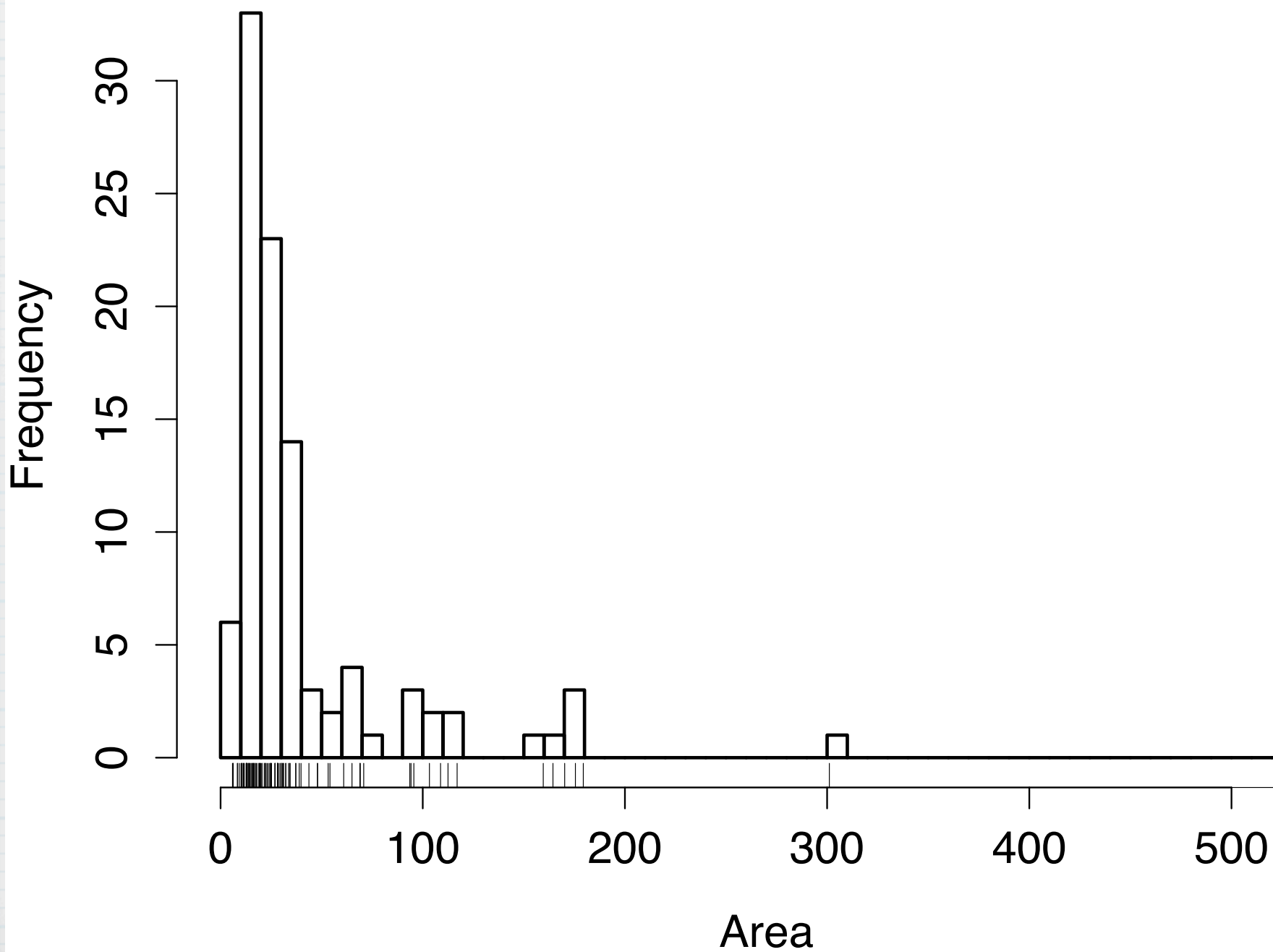
1/19/07

Summary of our sampling experiment

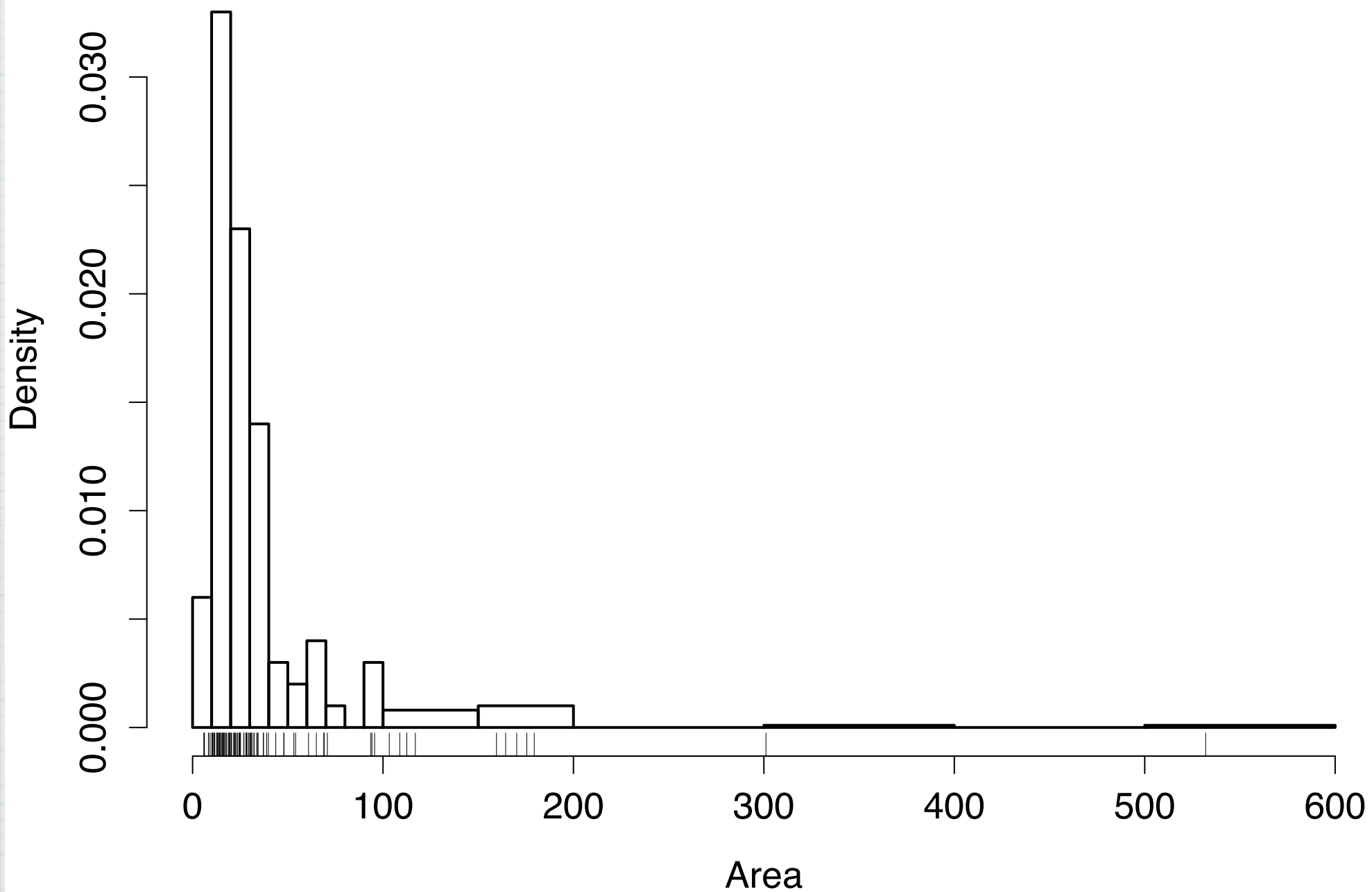
Histogram of areas of 100 blocks



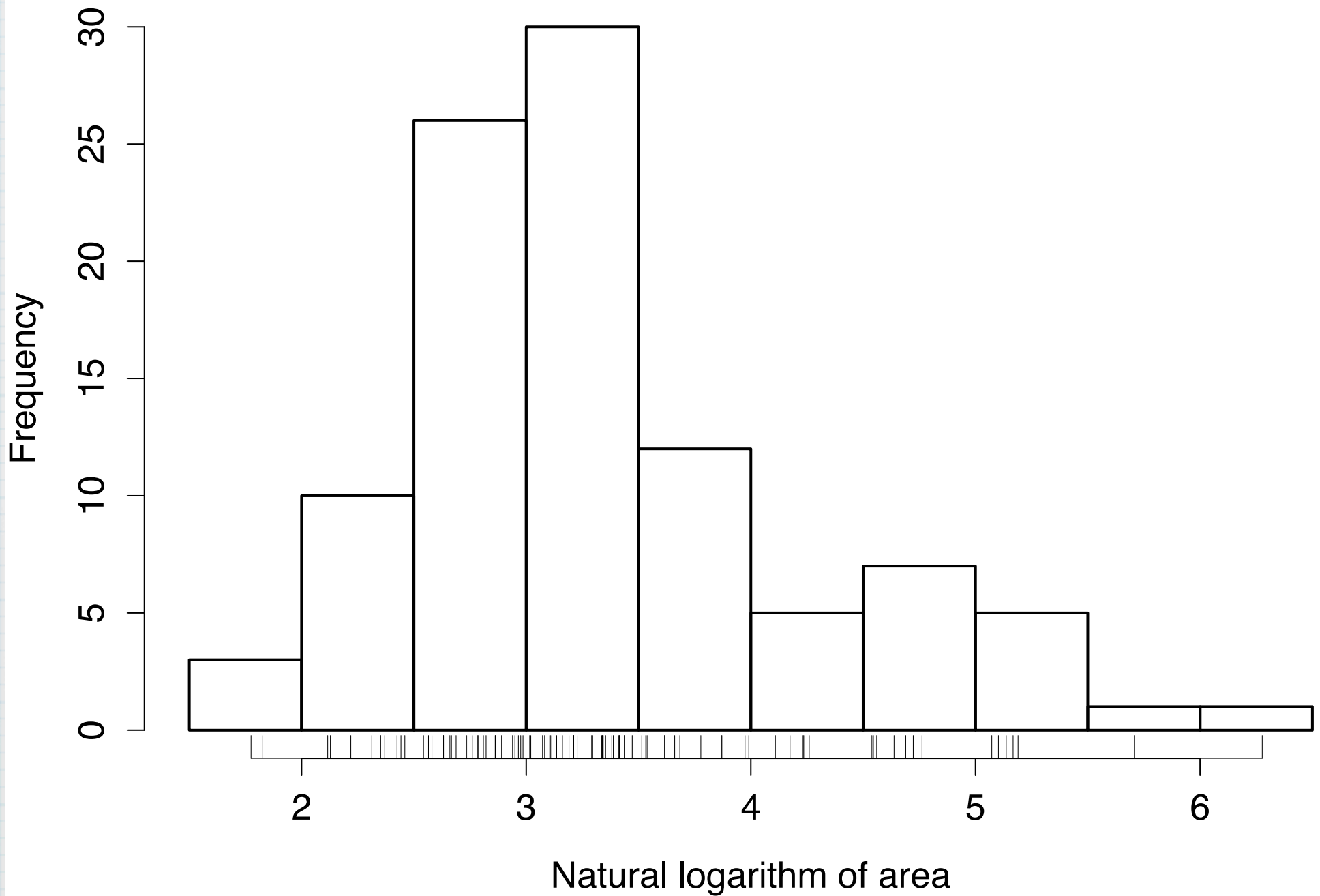
Histogram of areas of 100 blocks with rugplot



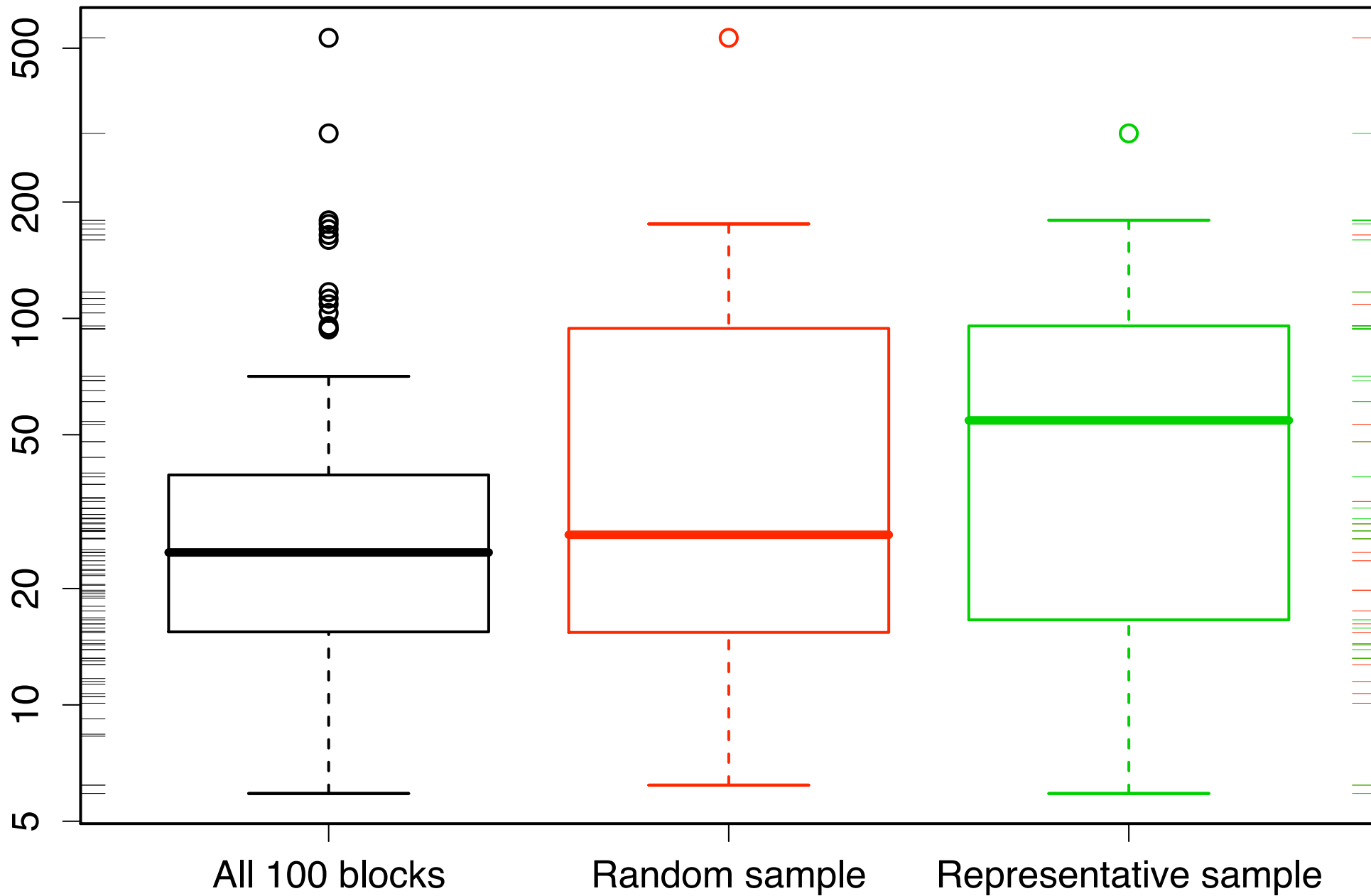
Histogram of areas of 100 blocks with rugplot



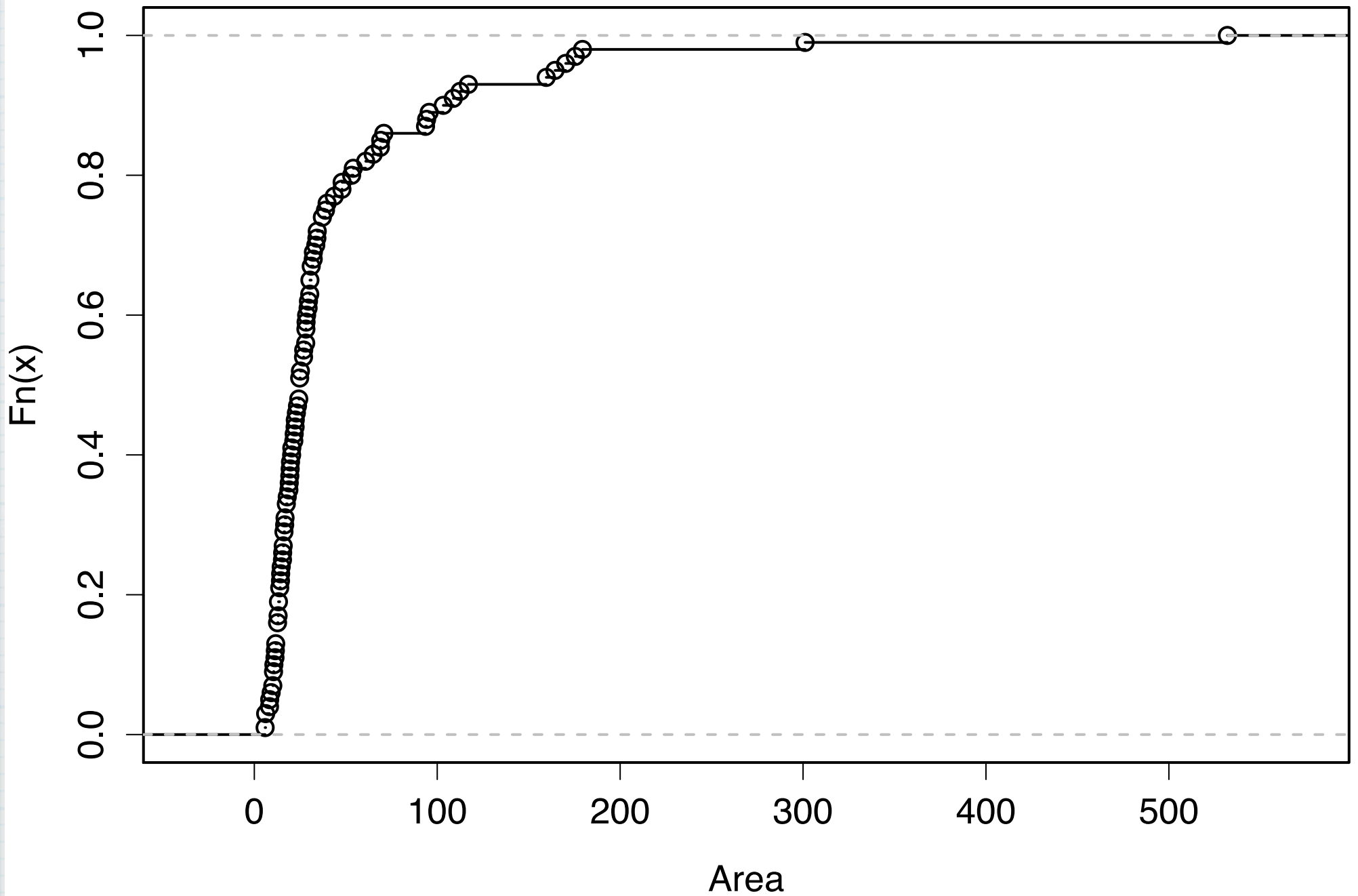
Histogram of log areas of 100 blocks with rugplot



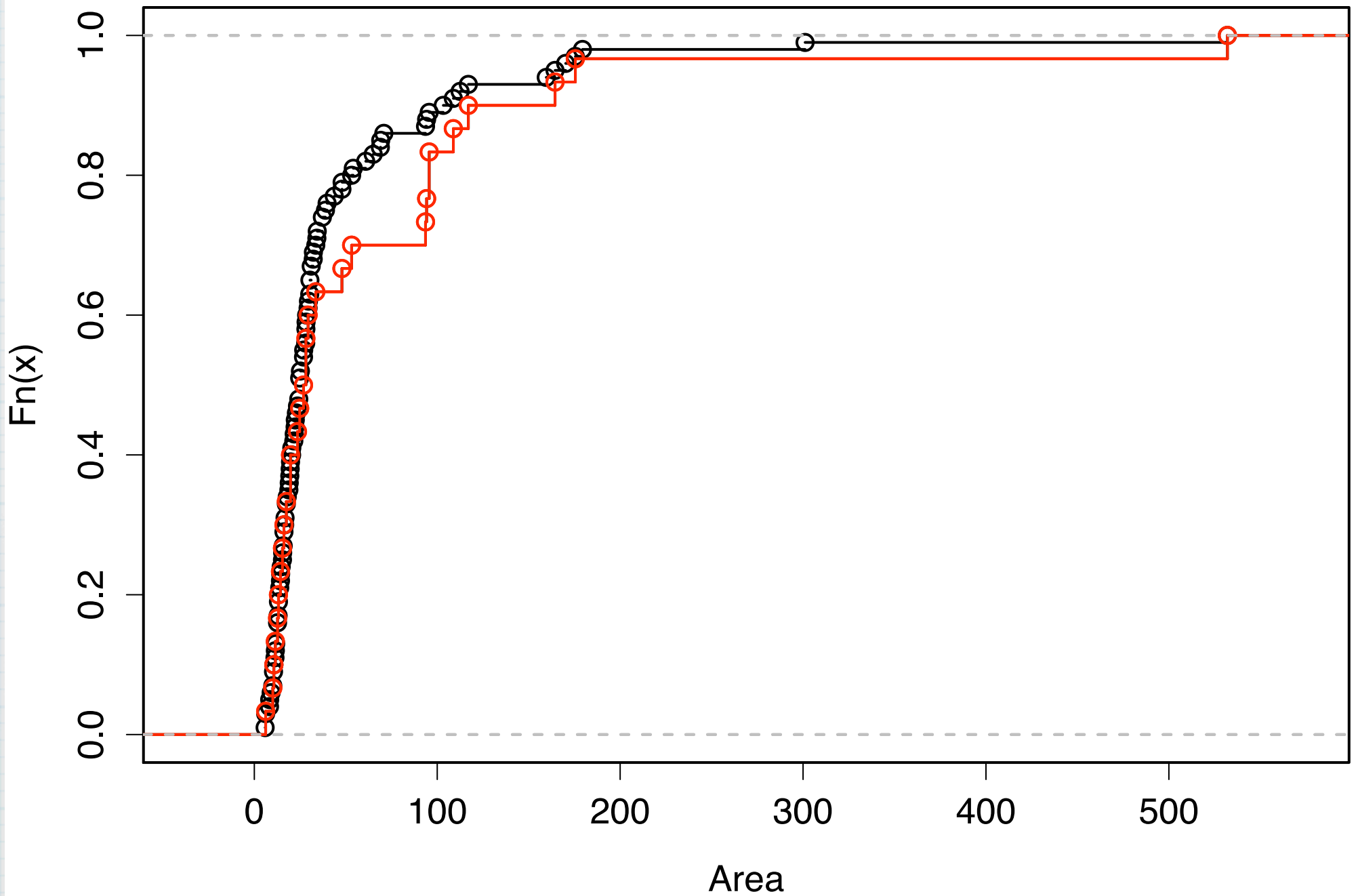
Boxplots of Areas



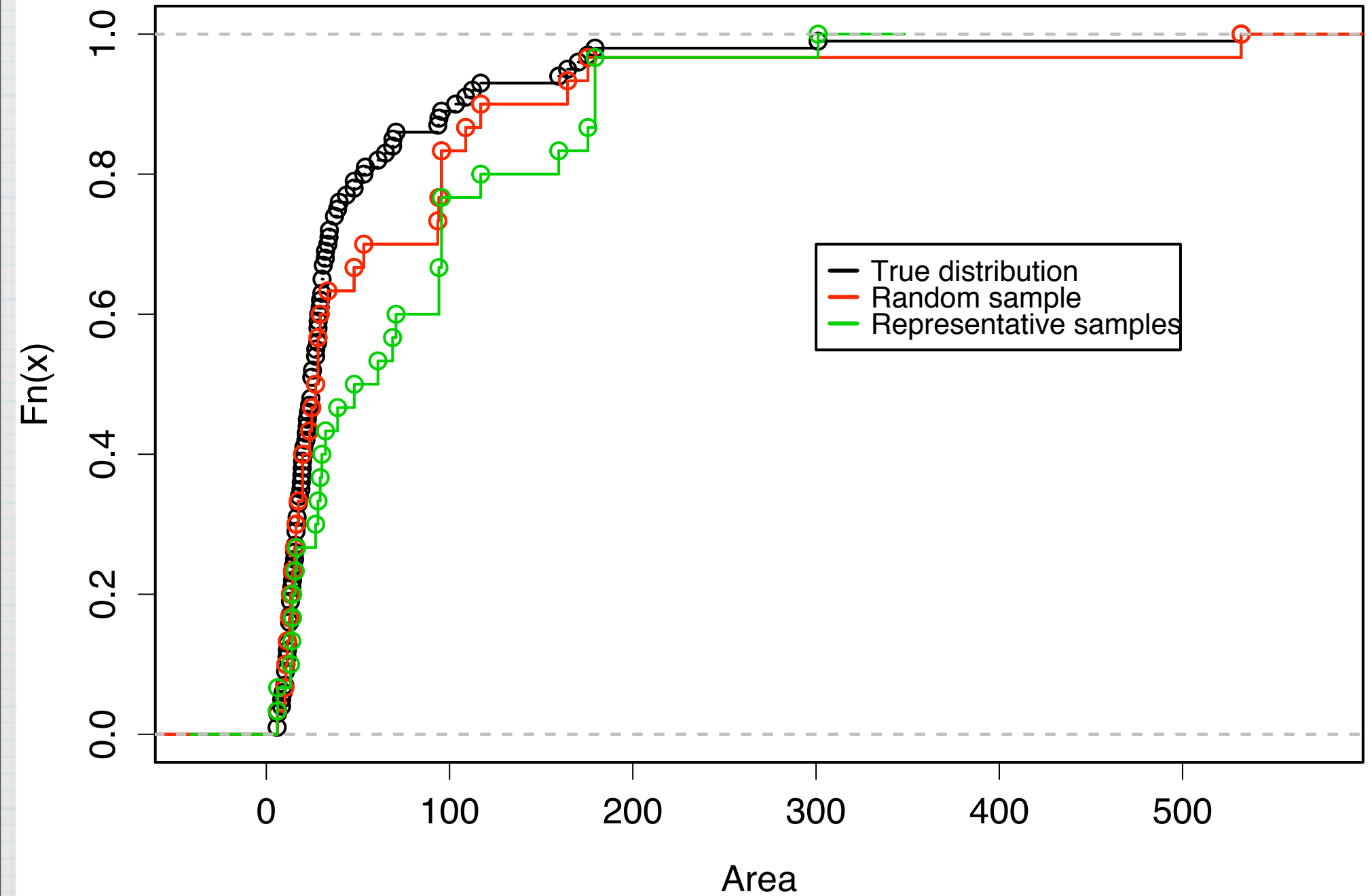
Empirical distribution function of Areas



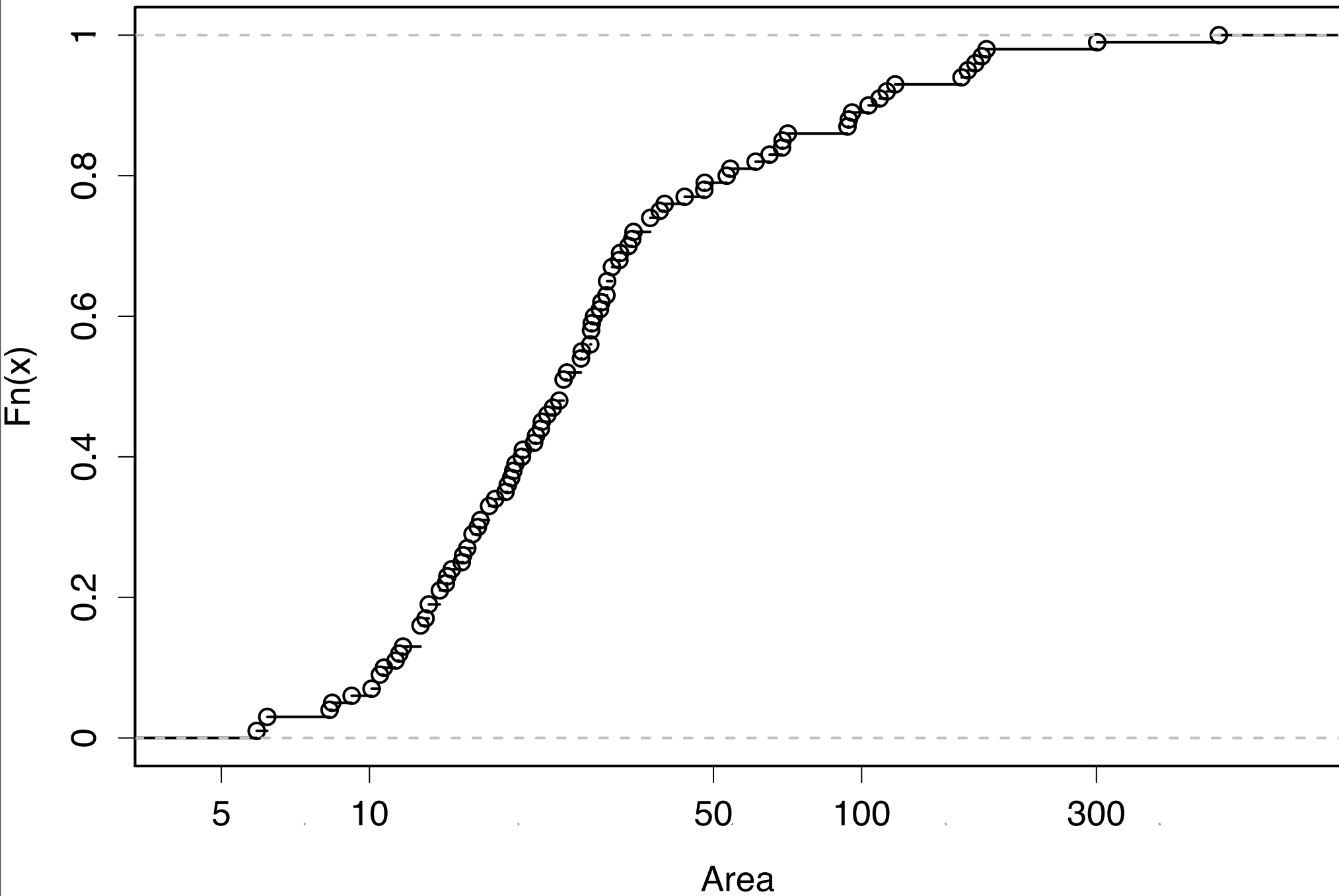
Empirical distribution function of Areas



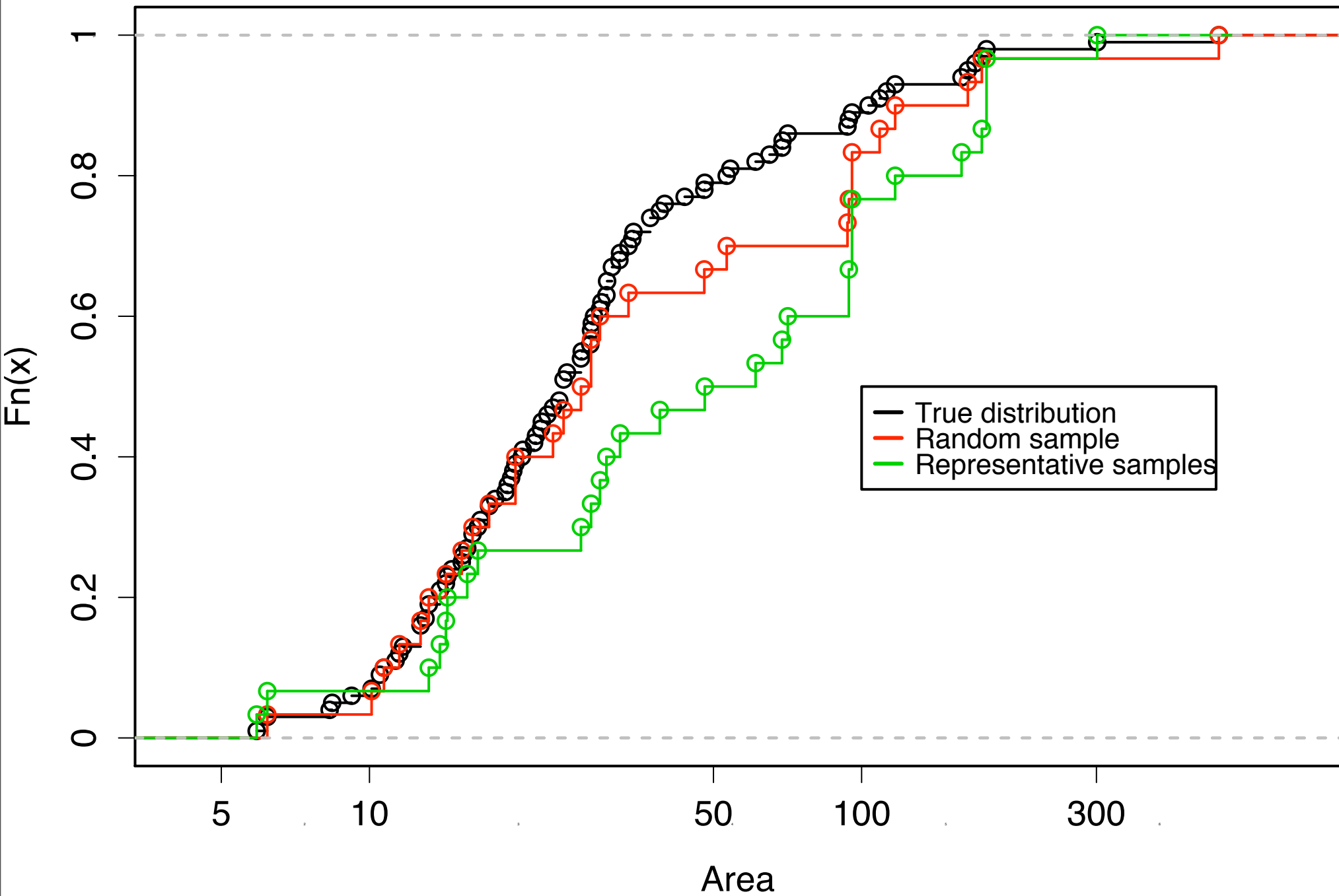
Empirical distribution function of Areas



Empirical distribution function of Areas



Empirical distribution function of Areas



Inferring (Estimating) Means

- * Sampling from a population or from a probability distribution is like drawing from a box
- * Sums or averages (or other functions) of the sample have a “sampling distribution”
- * If it's a simple random sample (with or without replacement) the expectation of the sampling mean is the same as the mean of the numbers in the box.

10 weighings of unknown weight
average 10.5g. Known SD 2g,
errors normally distributed

- * What should you estimate for the true weight?
- * How confident should you be about that answer?



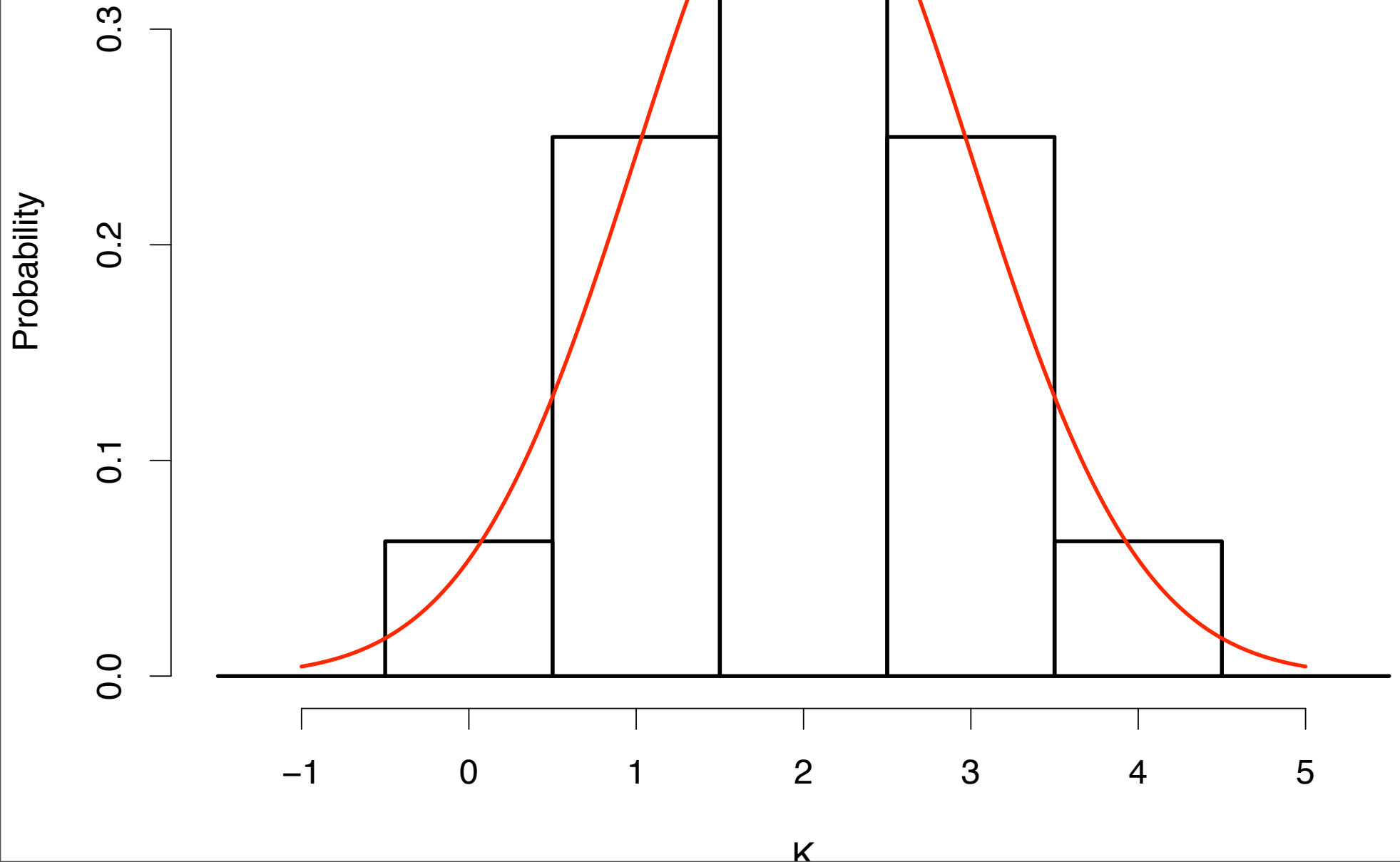
ESP experiment



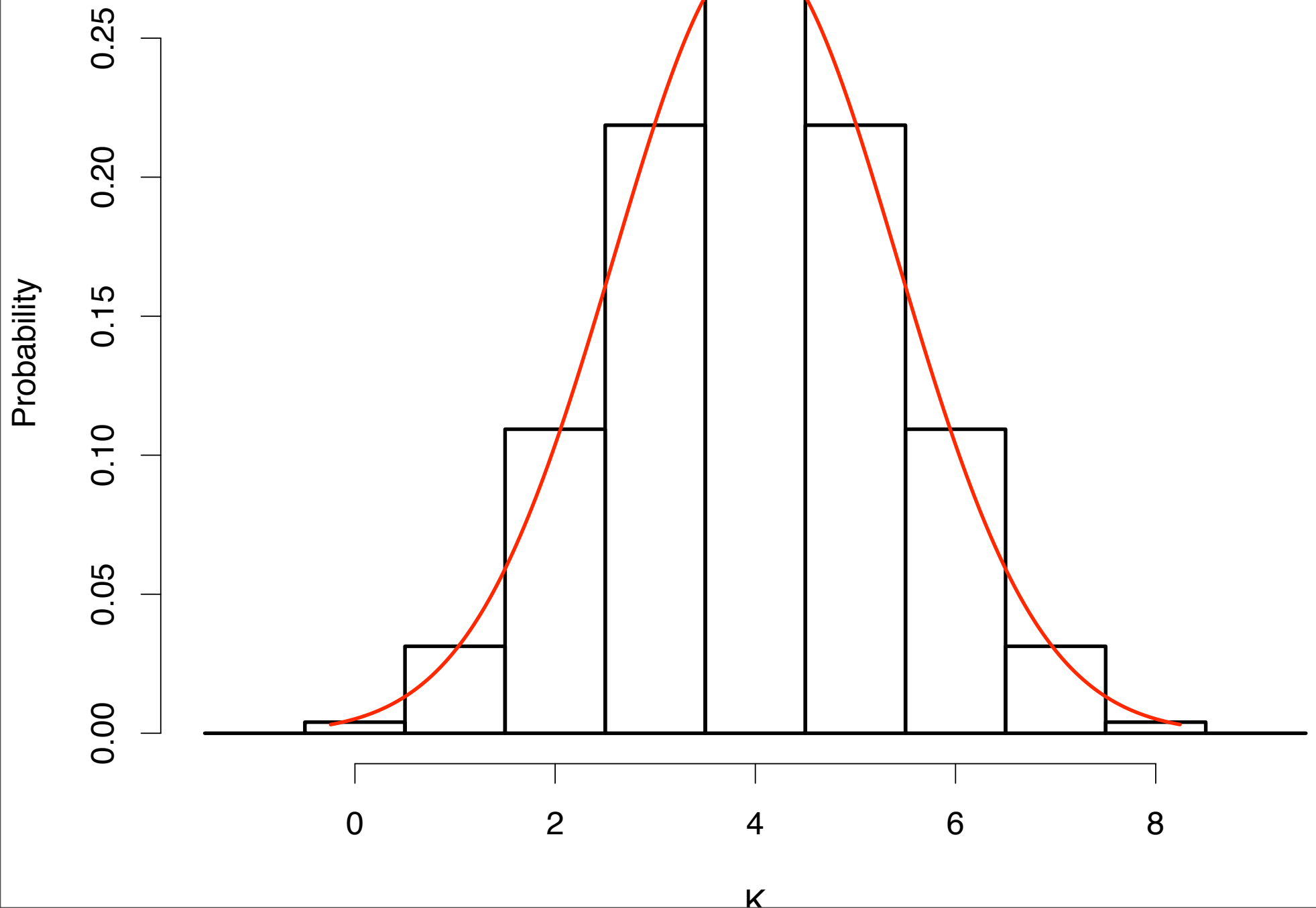
- * Charles Tart (1970s): 7500 (500x15) attempts on "Aquarius machine"
- * Subjects predict which of four lights will come on
- * Signal tells them if they were right.
- * 2,006 correct predictions in 7500 attempts

Normal approximation

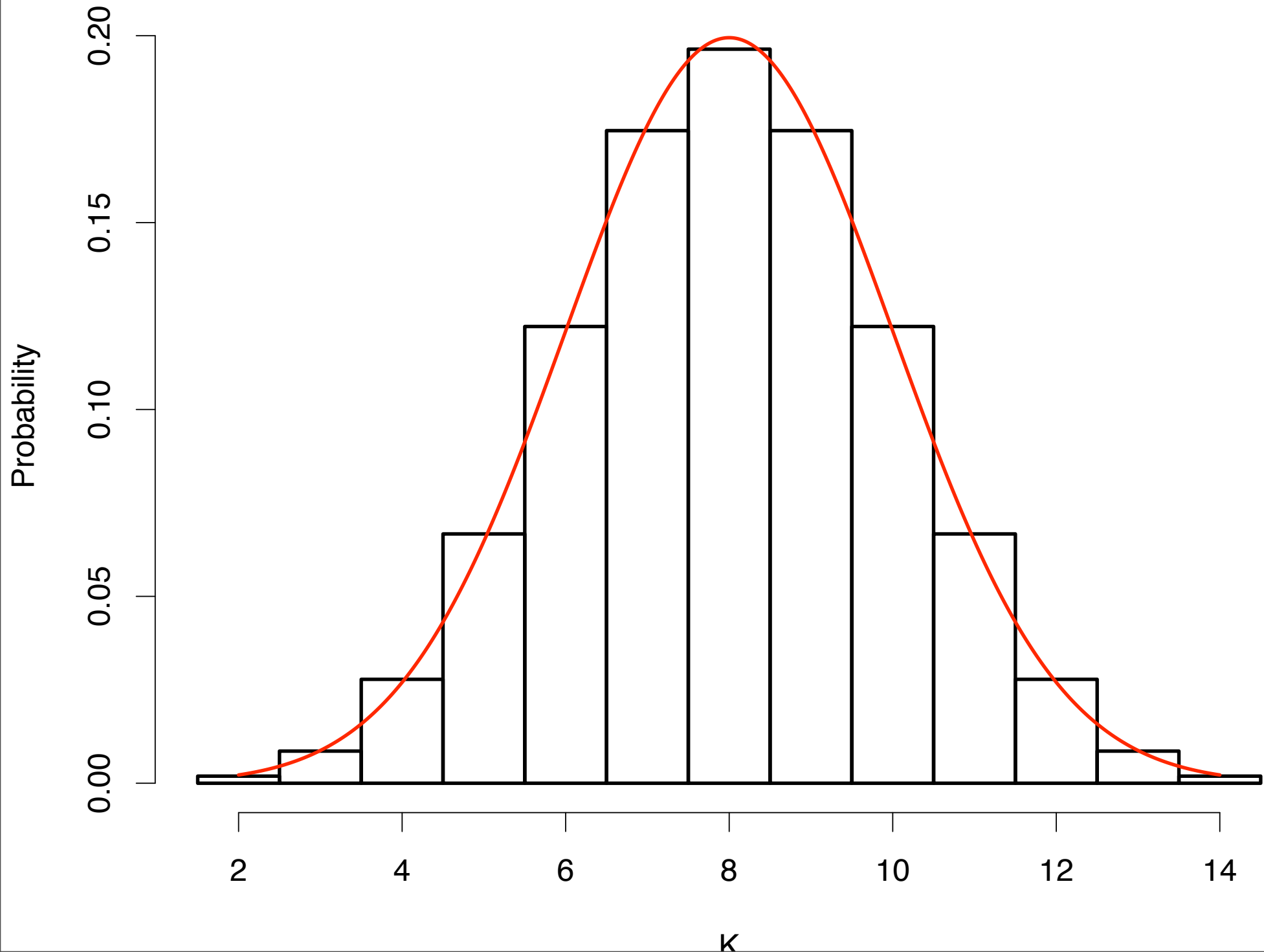
Binomial distribution with $p=0.5$ and $n=4$



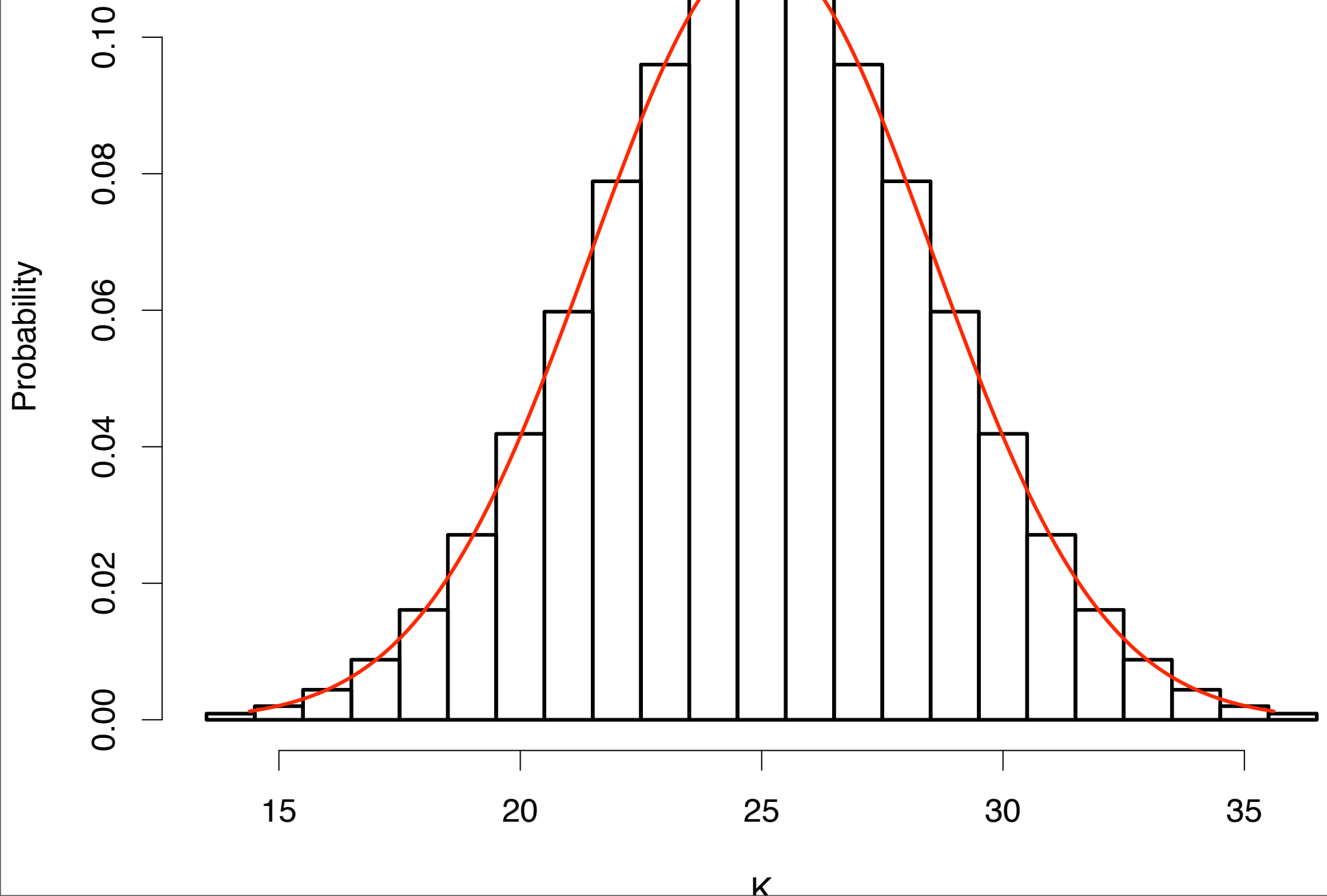
Binomial distribution with $p = 0.5$ and $n = 8$



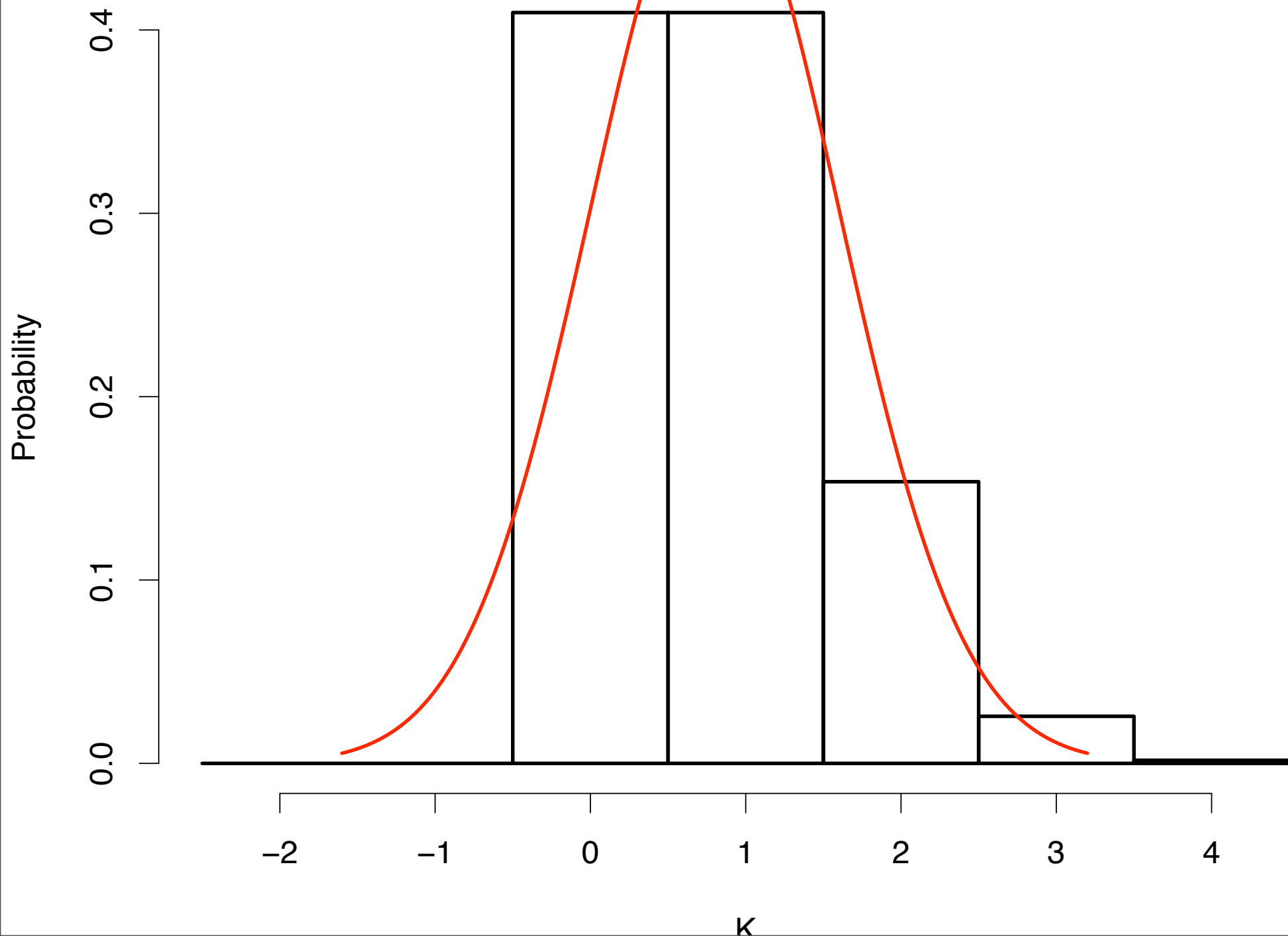
Binomial distribution with $p=0.5$ and $n=16$



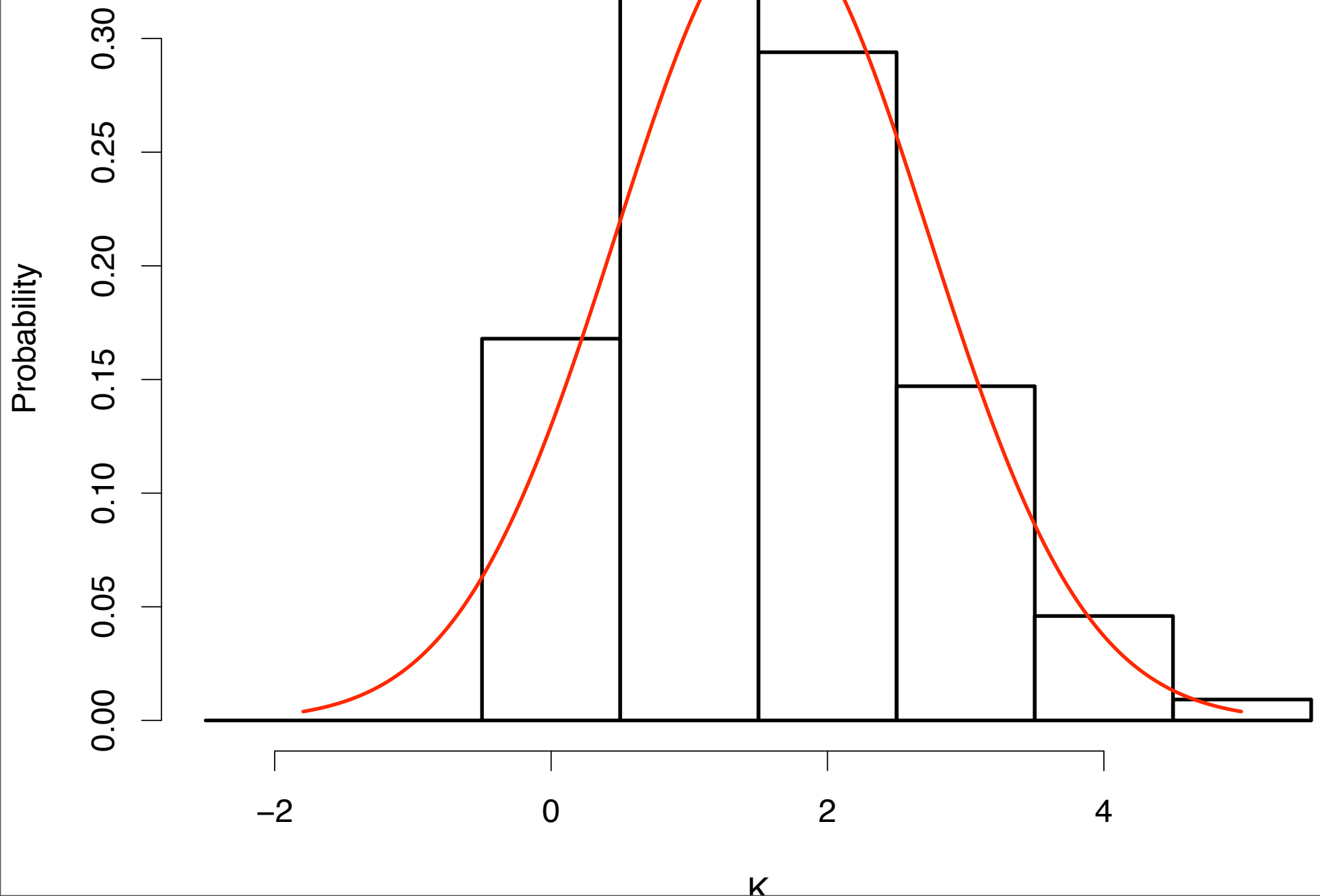
Binomial distribution with $p= 0.5$ and $n= 50$



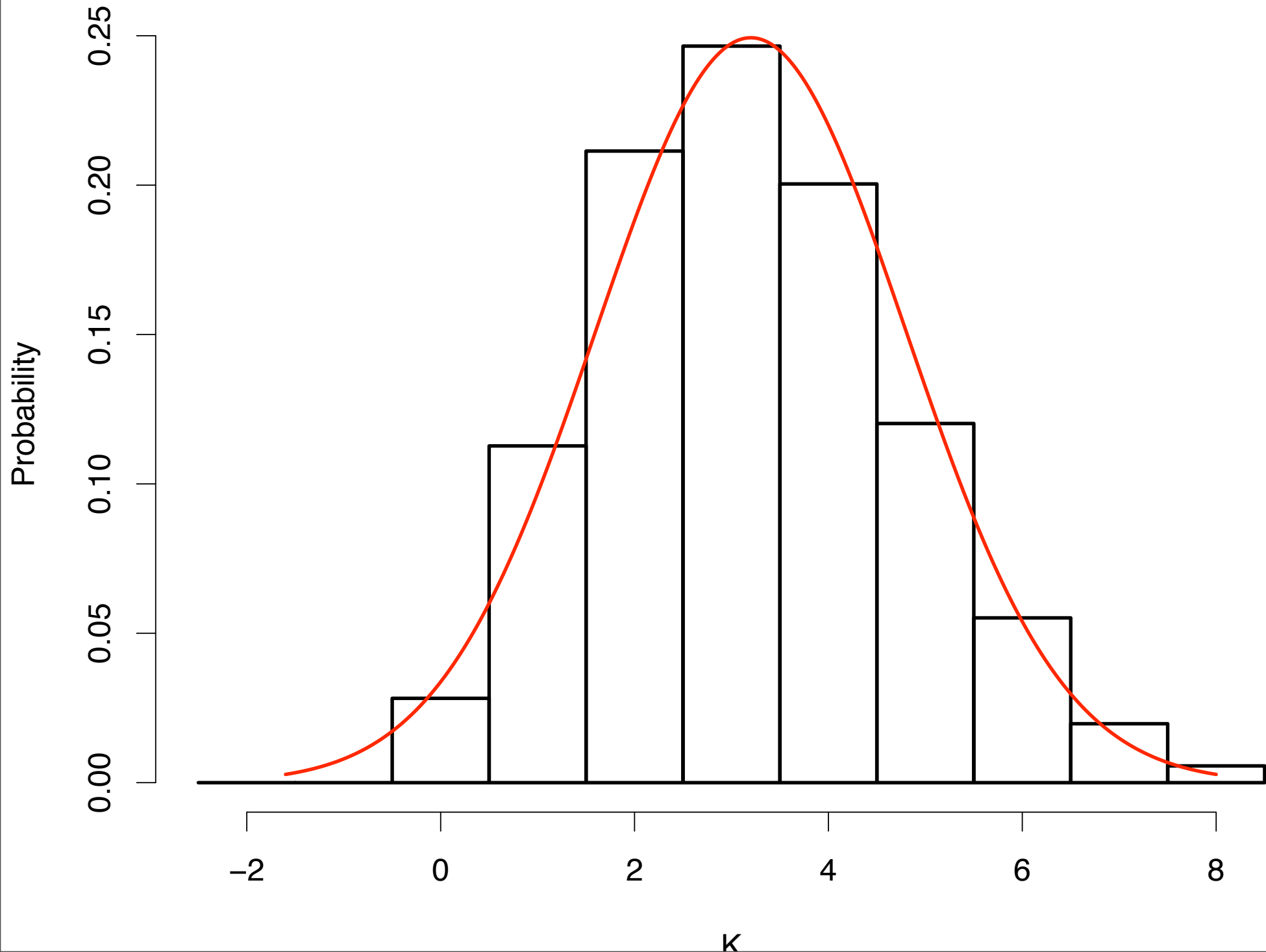
Binomial distribution with $p = 0.2$ and $n = 4$



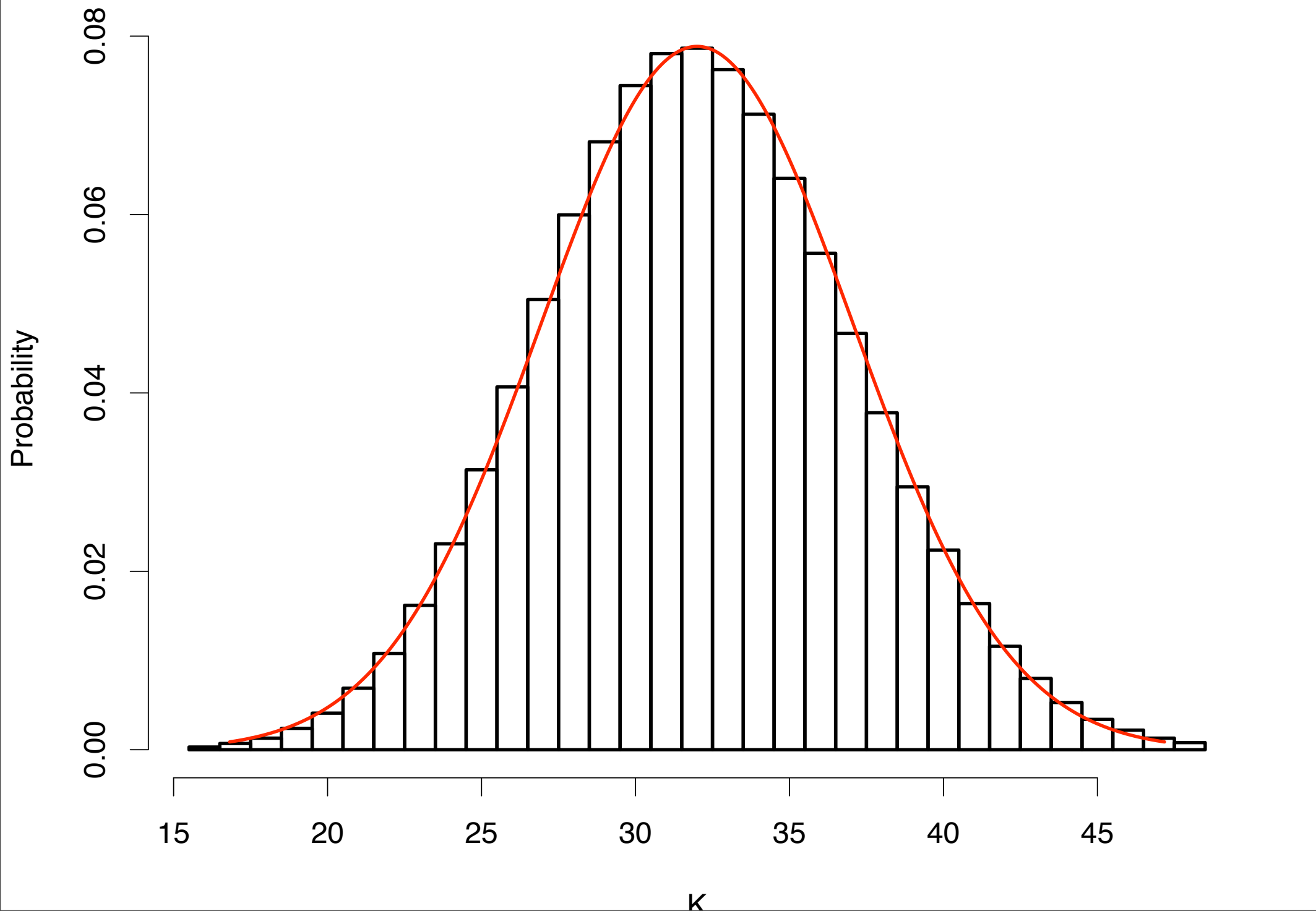
Binomial distribution with $p= 0.2$ and $n= 8$



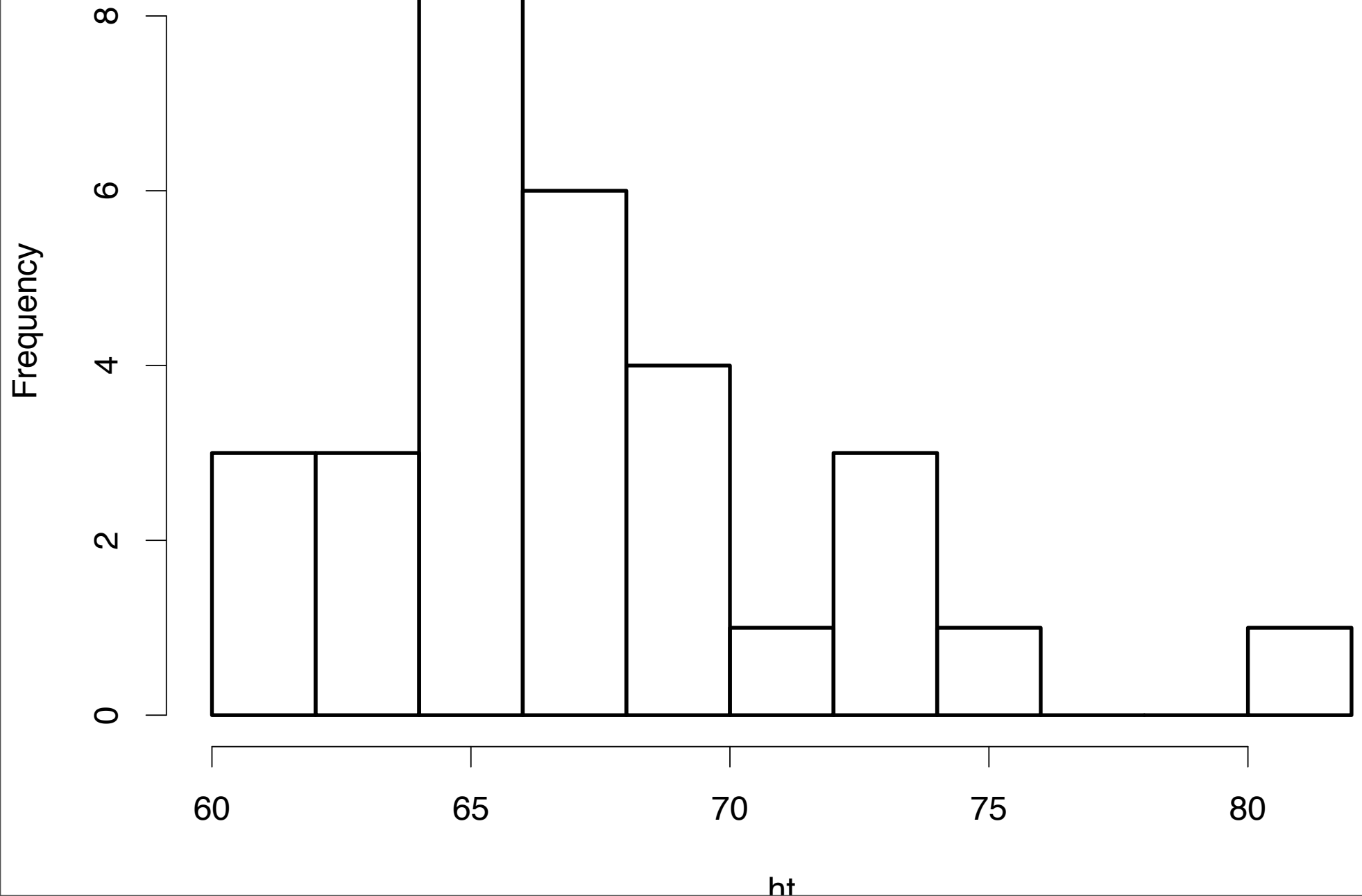
Binomial distribution with $p= 0.2$ and $n= 16$



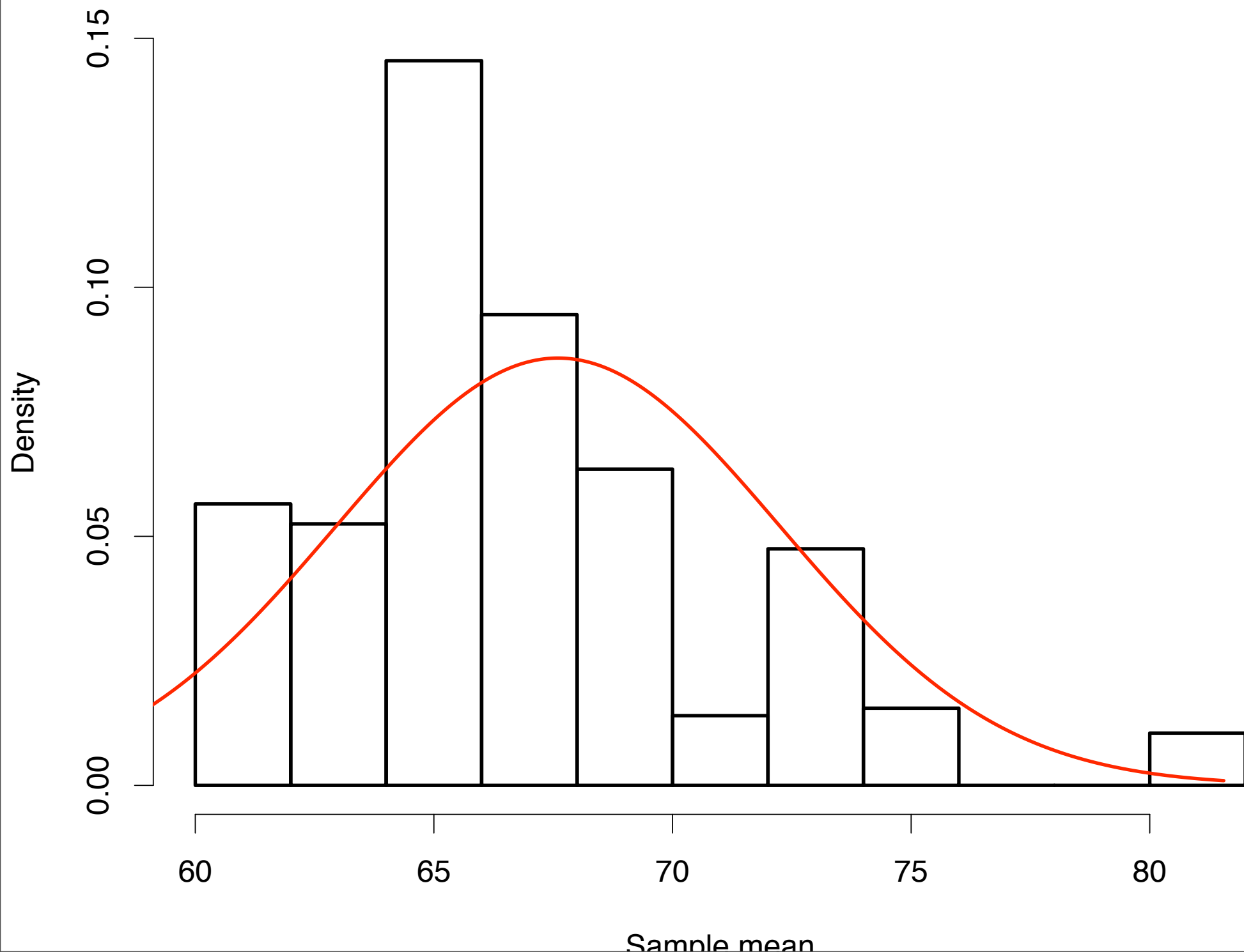
Binomial distribution with $p= 0.2$ and $n= 160$



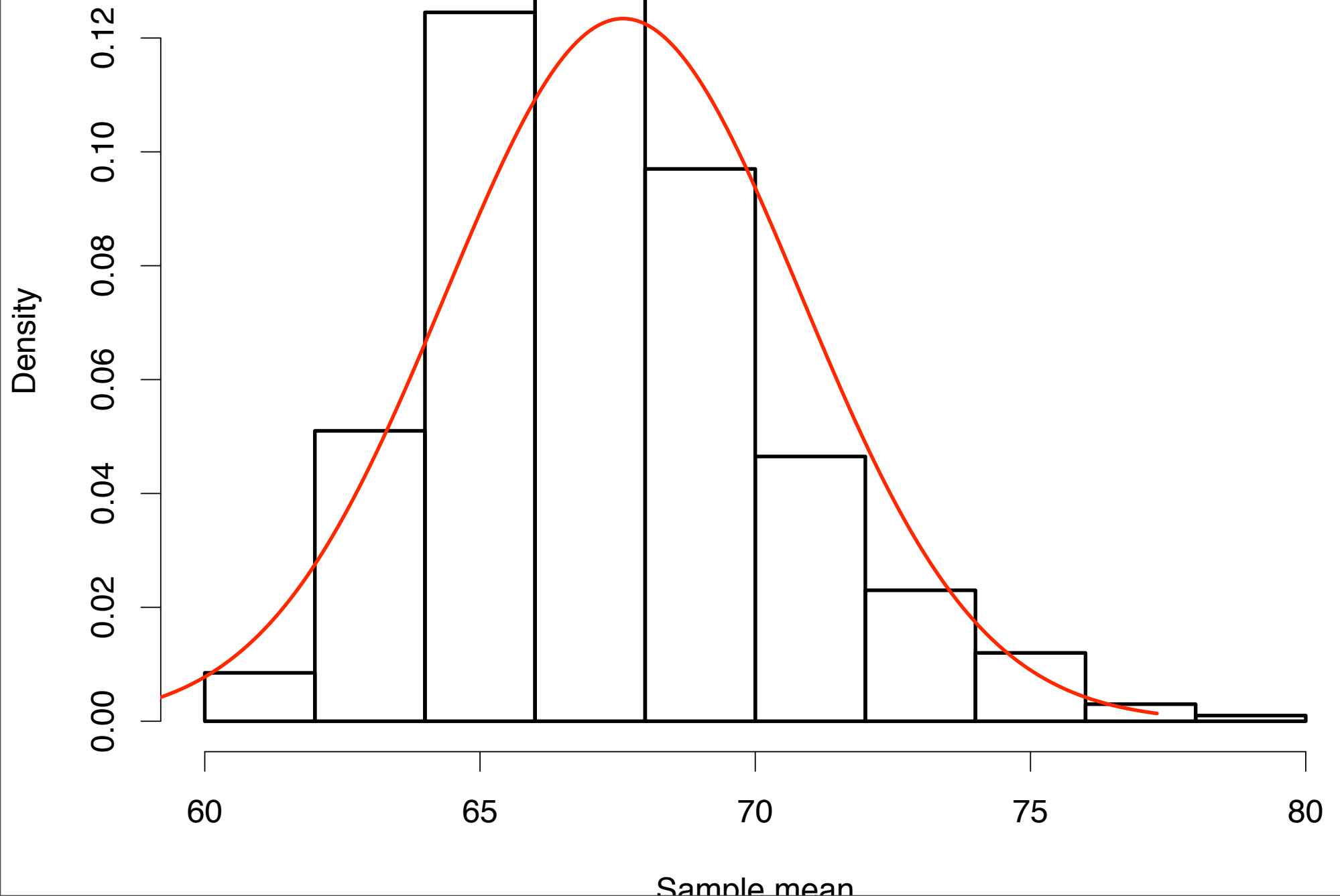
Histogram of class heights



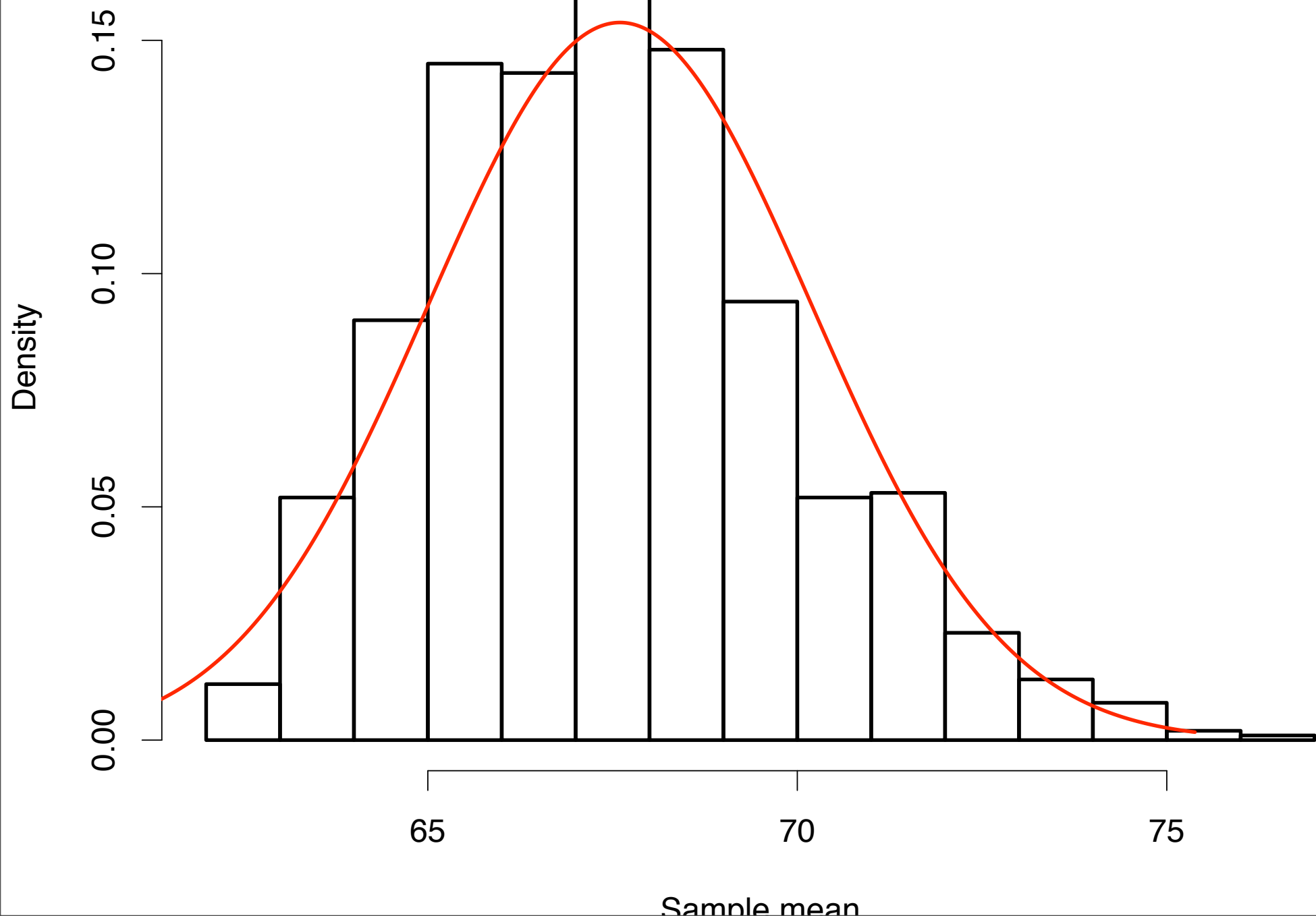
Histogram of 1000 samples of size 1



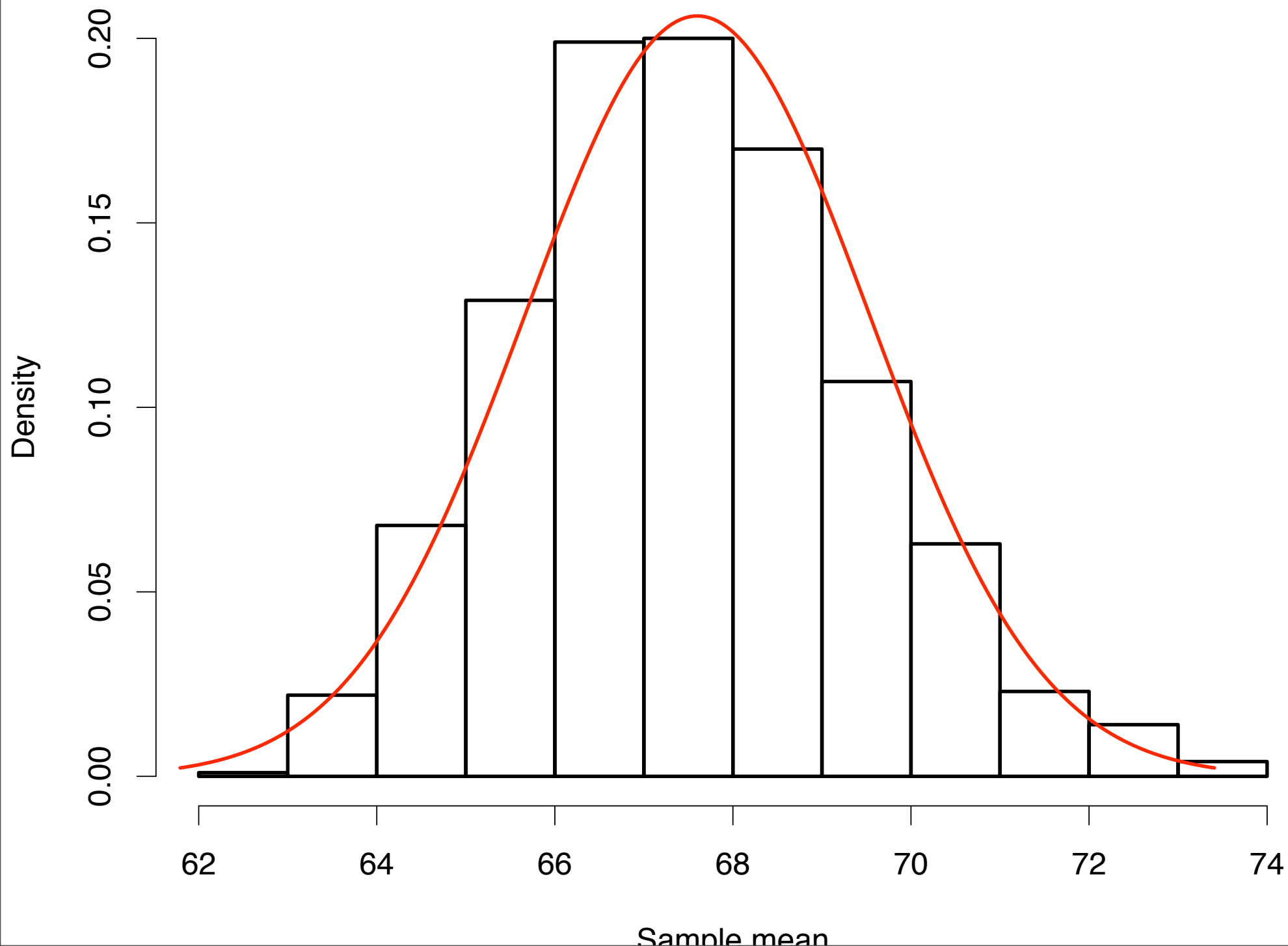
Histogram of 1000 samples of size 2



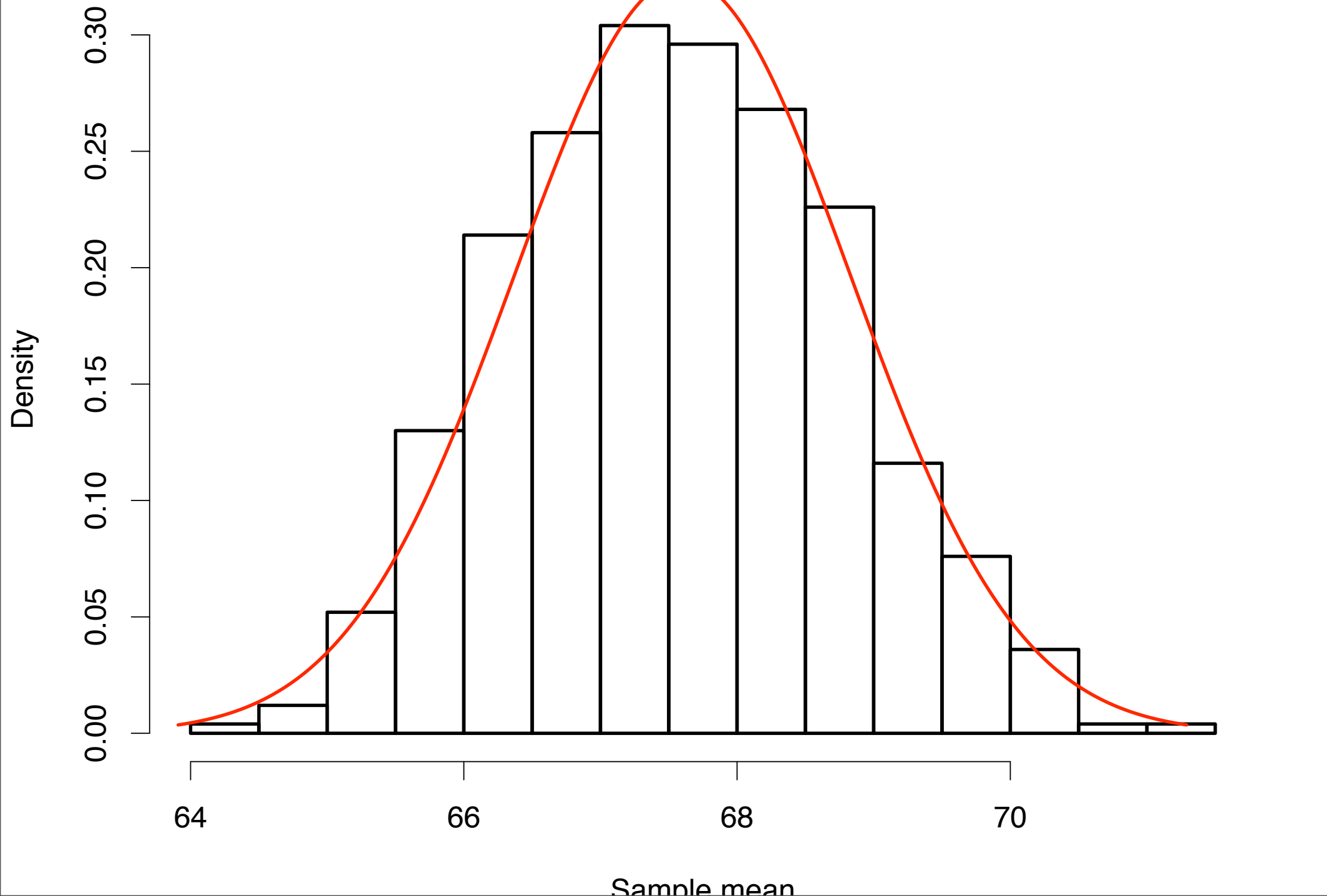
Histogram of 1000 samples of size 3



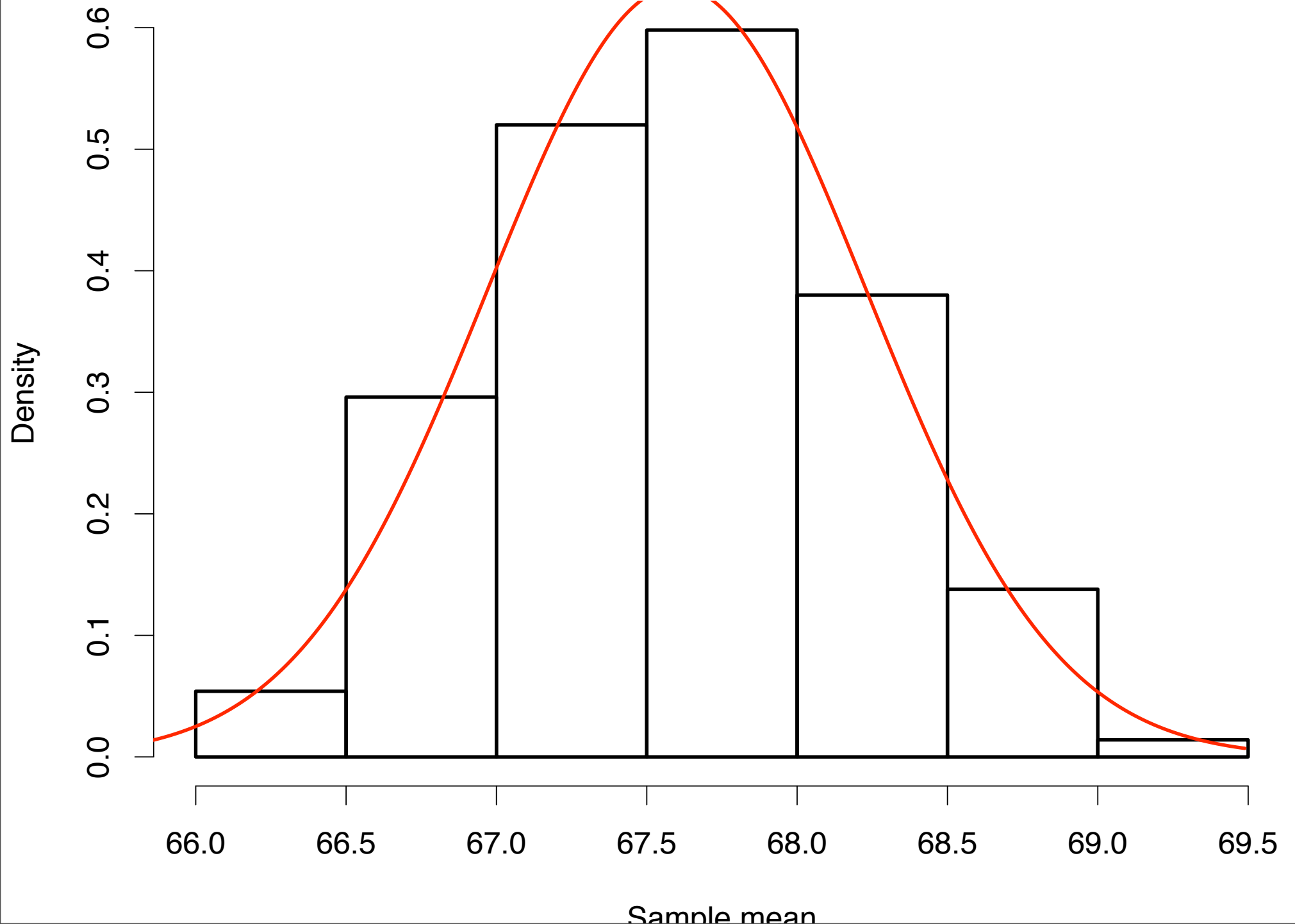
Histogram of 1000 samples of size 5



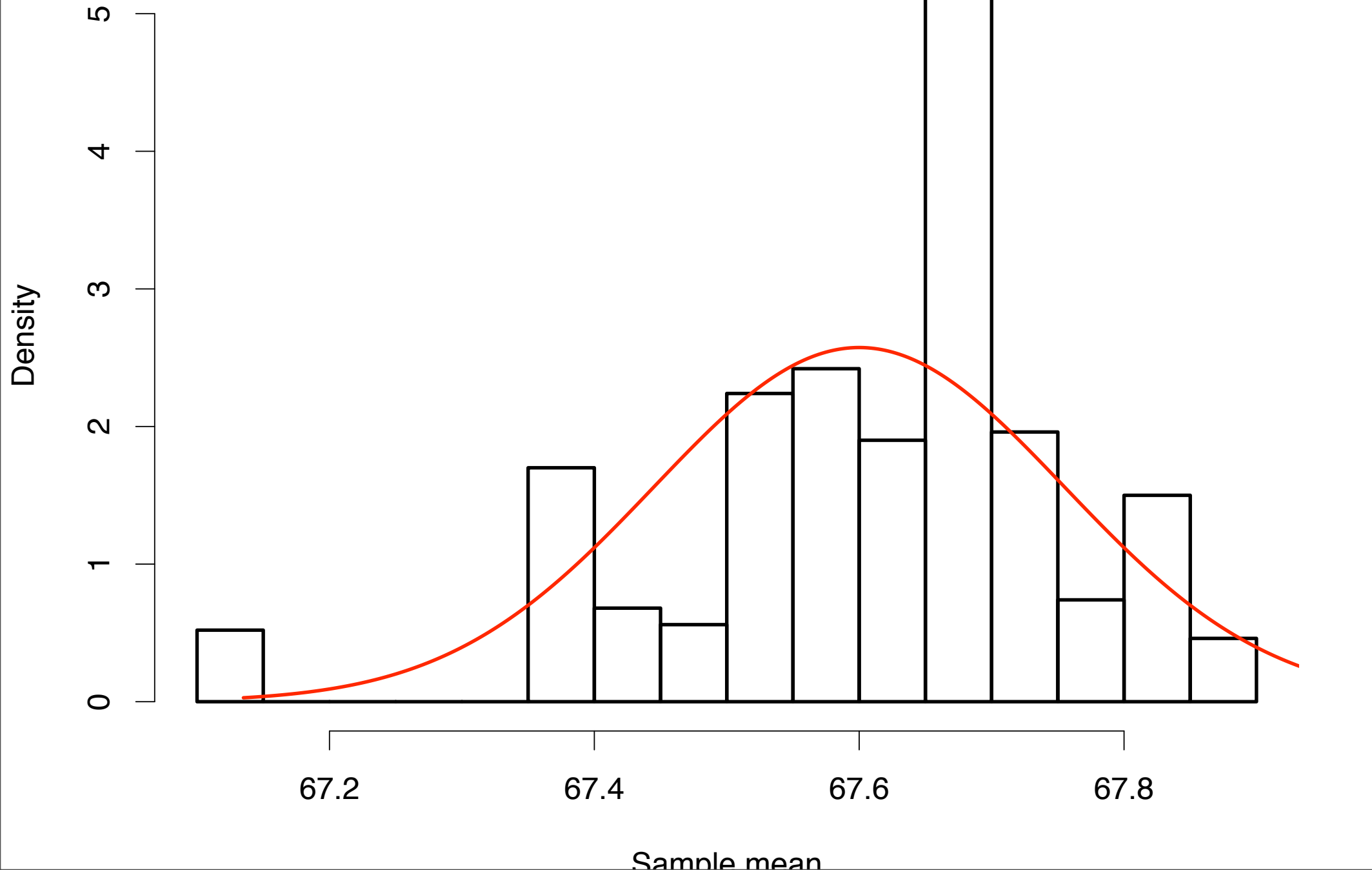
Histogram of 1000 samples of size 10



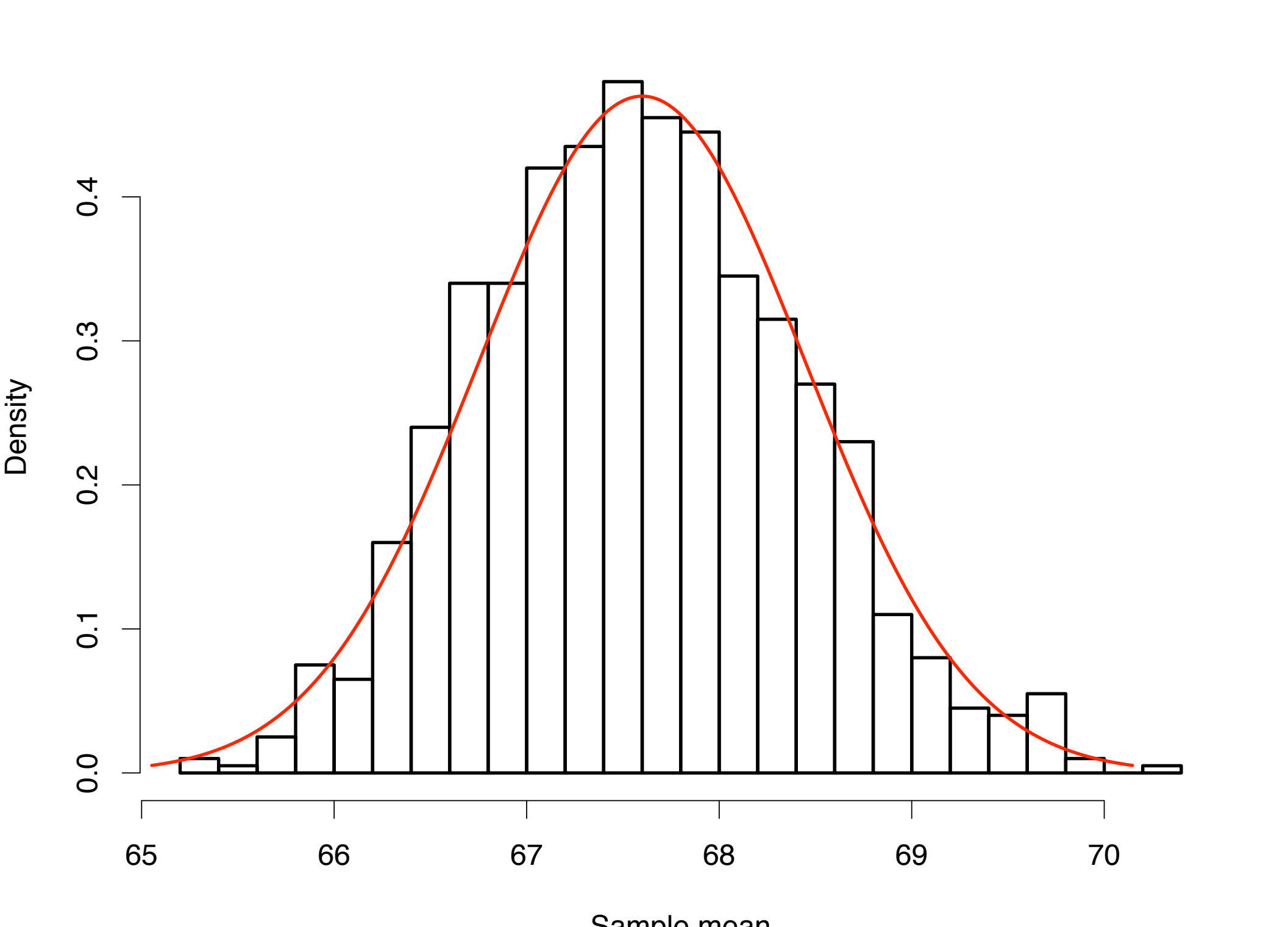
Histogram of 1000 samples of size 20



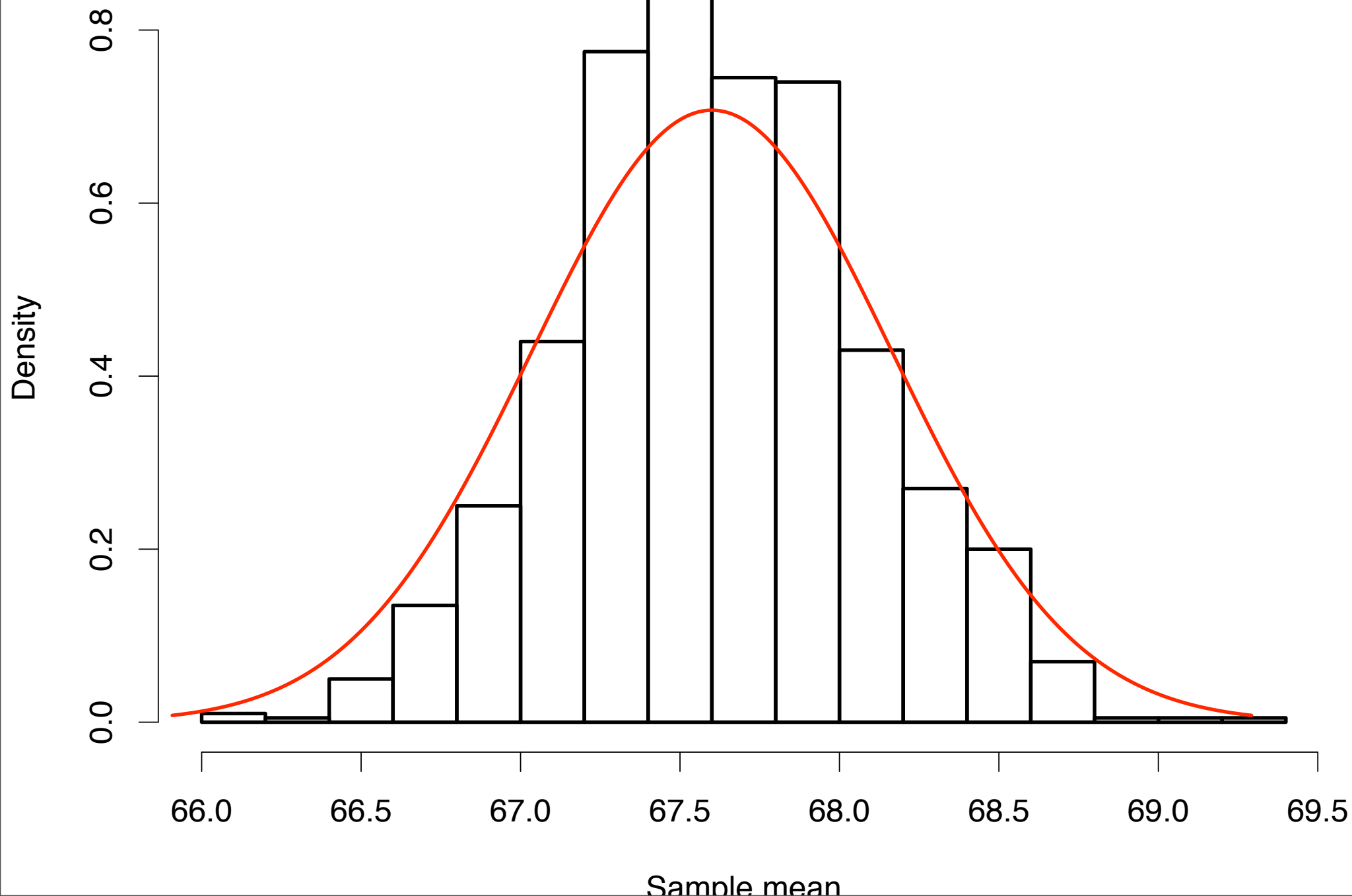
Histogram of 1000 samples of size 30



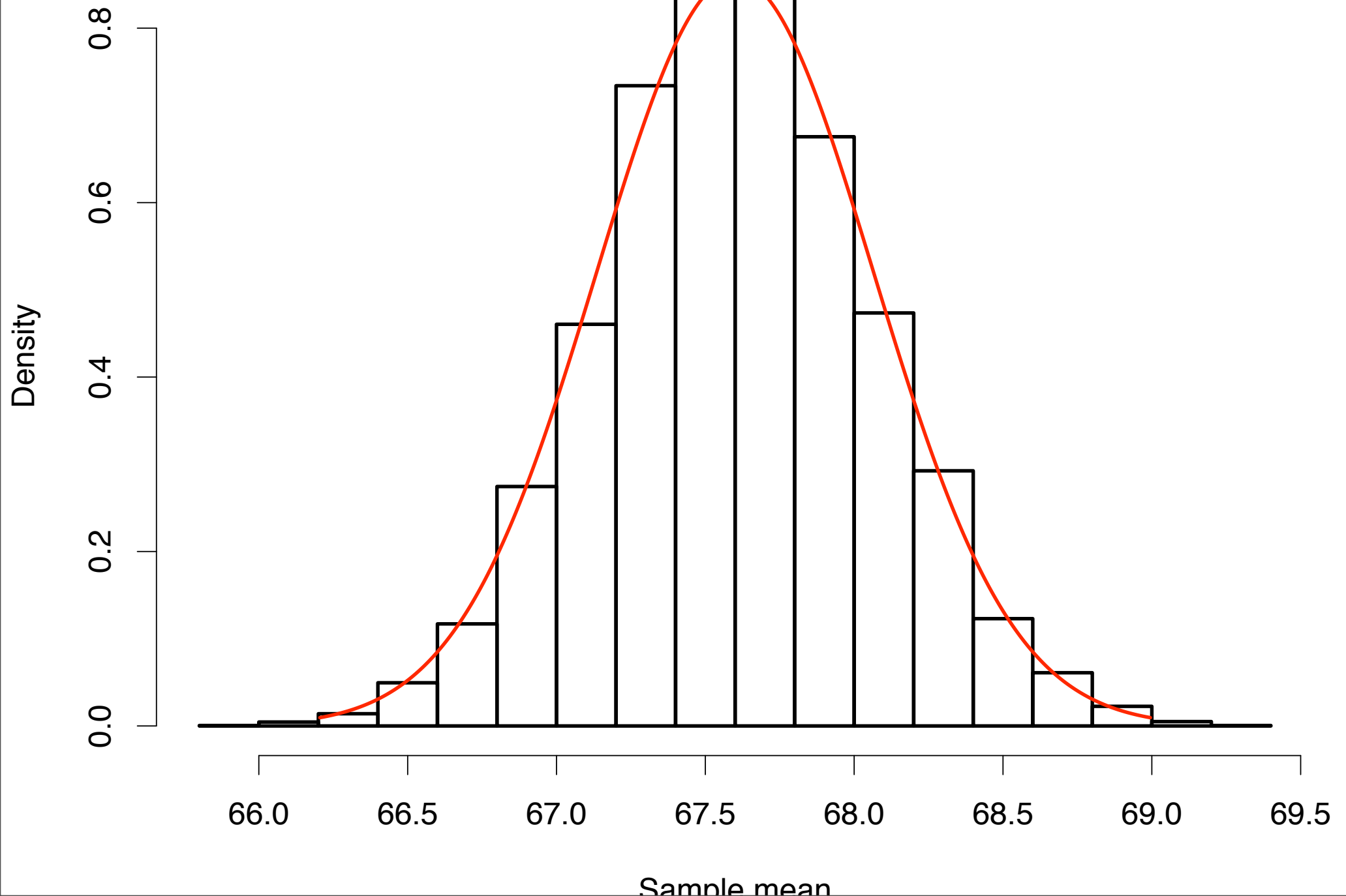
Histogram of 1000 samples of size 30 with replacment



Histogram of 1000 samples of size 100 with replacment



Histogram of 10000 samples of size 100 with replacment



Goals

- * Summarize the data
- * Model the source of the data
- * Use the data to infer details of the source

“How could the data have been different?”

- * Were data sampled from a larger population?
- * Was the population generated by a random process?

Summary

- * Data are assumed to derive from random processes
- * We use probability theory to make up models, compute implications
- * We use statistics to infer backward from data to the particular model
- * Results depend on the accuracy of the assumptions in the general model
- * Averaging reduces variance